

Martin Werner



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Deep Learning

with applications to point clouds

GEFÖRDERT VOM



Bundesministerium für Bildung und Forschung

Outline



- A Short History of Deep Learning
- Deep Learning Elements
 - Neurons
 - Neural Networks
 - Back Propagation and Gradient Descent
- Some Basic Deep Learning Architectures
- Dealing with Point Clouds
- And now? How would I?



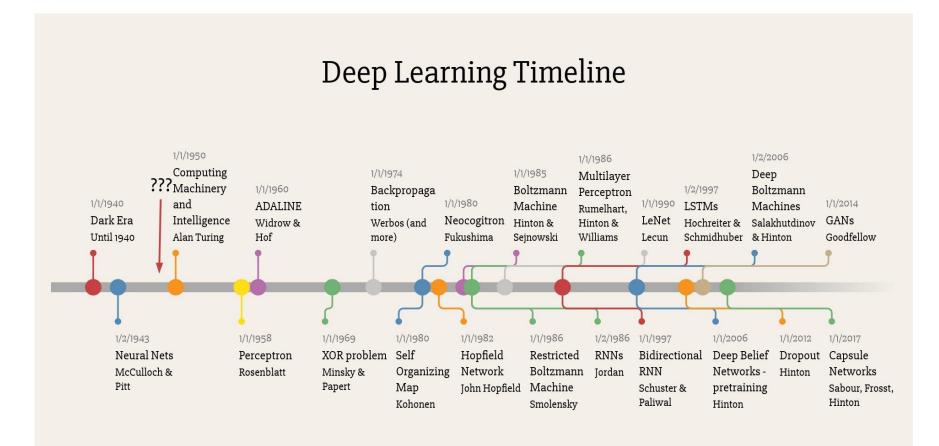
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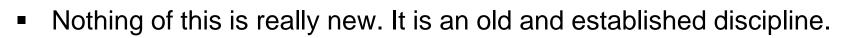
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A Short History of Deep Learning





Made by Favio Vázquez



- The current hype comes from several factors
 - Advances in computational performances (GPUs, TPUs)
 - Creation of Huge Datasets
 - (Smaller) Advances in Stochastic Gradient Decent
 - Novel Ideas about Regularization
 - Novel Ideas for Capacity (Weight) Reduction
 - Convolutional Neural Networks
- But, Deep Learning is not very powerful per se:
 - Energy Consumption
 - Dataset Creation Cost
 - Performance of the Deployed System
 - Understandability and Certification of Systems



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Deep Learning Elements



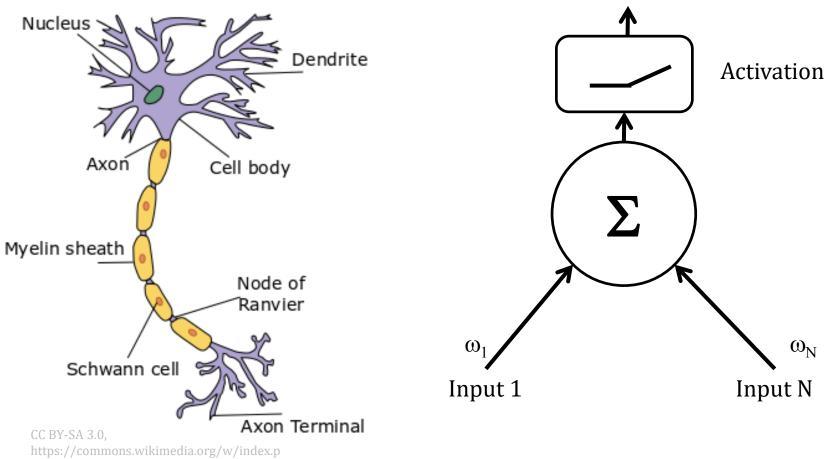
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Neurons and Neural Networks





The simplest Neuron is a linear one.

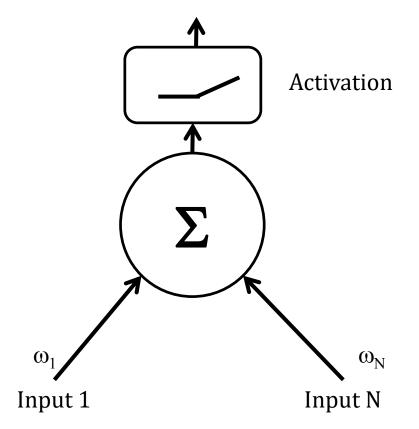
This means

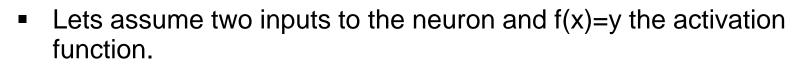
- Activation Function is linear
- A bias term is added
- Then, we can write the output as

$$\sum_{i=1\dots N} \omega_i x_i + b$$

 For simplicity, the bias is often made an artifical input to the system such that it reads even simpler (w_0 = 1, x_0 = b)

$$\sum_{i=0..N} \omega_i x_i$$





- Question: What can we represent in this way:
- Answer: Lets calculate a bit (with explicit bias)

$$\sum_{i} \omega_i + b = \omega_1 x_1 + \omega_2 x_2 + b$$

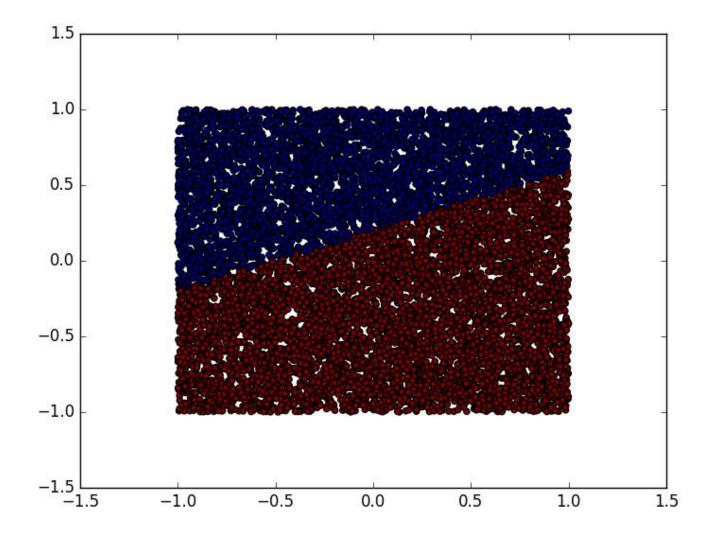
- Now, for binary classification, we need a simple decision rule. What about (output > 0)
- Then, we can learn sets that have the structure

$$\sum_{i} \omega_i + b = \omega_1 x_1 + \omega_2 x_2 + b \ge 0$$

• This is easily seen to be a split along a line in space. Lets do this

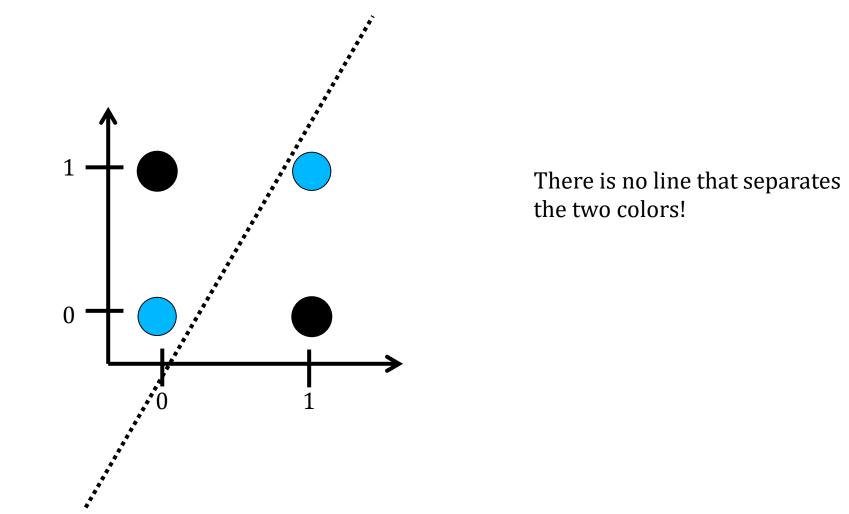






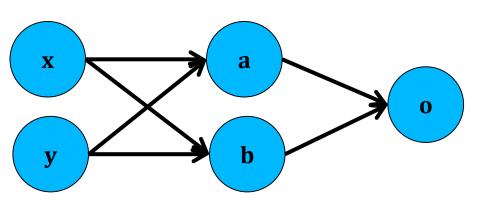
However, XOR is impossible to represent with a single neuron







This architecture has an bias term for all hidden nodes (a) and the output node which is hidden.



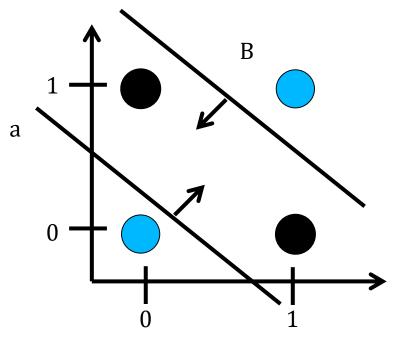
That is, there are nine weights!

Each of the early neurons decides

a) Above the line

b) Below the line

The last neuron calculates A AND B, which is easily possible !



Assignment: Find a set of weights for the network to model XOR



Now, for a long time, no real progress was made. People got frustrated, left the field. The frustration points were:

- Finding optimal weights is NP-complete exponential runtime
- While solving XOR is possible with a MLP, it is impossible to train, because the expected output of the inner connections is unknown.
- Many people turned away from this part of machine learning
- Dates are difficult to assign as related machine learning techinques are still evolving:
 - Starts about the time that the implications of the unsolvability of XOR for general intelligence become clear

Challenge Problem has been identified: train MLP

- Ends about the time where multilayer perceptrons are successfully trained
 - Challenge Problem has been fully solved without avoiding it.



Learning representations by back-propagating errors

David E. Rumelhart^{*}, Geoffrey E. Hinton[†] & Ronald J. Williams^{*}

* Institute for Cognitive Science, C-015, University of California, San Diego, La Jolla, California 92093, USA † Department of Computer Science, Carnegie-Mellon University, Pittsburgh, Philadelphia 15213, USA

We describe a new learning procedure, back-propagation, for networks of neurone-like units. The procedure repeatedly adjusts the weights of the connections in the network so as to minimize a measure of the difference between the actual output vector of the net and the desired output vector. As a result of the weight



- Where do the weights come from?
 - Finding the optimal weights is NP-complete (that is, as hard as the TSP; Blum and Rivest, 1992)
 - Fortunately, we can find a sufficient set of weights through back propagation (e.g., Rumelhart et al. (1985))
- First, we compare the output of a forward pass with the expected value.
- Then, we slightly adjust each of the weights backwards in the network by a very small amount.
- We do this over and over again (training)
- We do so, because the error function we chose is differentiable and sufficiently smooth such that the local direction of error reduction is sensible globally (which need not be the case)



Forward Pass

- All units within a layer have their values set in parallel
- Next layer only after first layer has completely been computed

Layer Function needs to

- Have bounded derivative only
- However, linear aggregation of the input before applying one nonlinear function simplifies learning procedure

Total Error Function

•
$$E = \frac{1}{2} \sum_{c} \sum_{j} (y_{j,c} - d_{j,c})^2$$

 Idea: Use Gradient Decent of this with partial derivatives with respect to each and every weight.



Let us fix a single case c. Then

•
$$\frac{\partial E}{\partial y_j} = y_j - d_j$$

Now, let x_j denote the activity of a unit in the forward pass. Then use the chain rule

•
$$\frac{\partial E}{\partial x_j} = \frac{\partial E}{\partial y_j} \cdot \frac{\partial y_j}{\partial x_j}$$

Now, with an activity function of $y_j = \frac{1}{1+e^{-x_j}}$ we can calculate and substitude the second factor:

•
$$\frac{\partial E}{\partial x_j} = \frac{\partial E}{\partial y_j} \cdot y_j (1 - y_j)$$

 This means, we know how the total input of node x_j changes the total error for this case. But as the total input is a linear sum of the inputs, we can compute



• $\frac{\partial E}{\partial w_{ij}} = \frac{\partial E}{\partial x_j} \cdot \frac{\partial x_j}{\partial w_{ij}} = \frac{\partial E}{\partial x_j} \cdot y_i$

• Und analog dazu können wir auch diese Ableitung für y ausrechnen:

•
$$\frac{\partial E}{\partial y_i} = \frac{\partial E}{\partial x_j} \cdot \frac{\partial x_j}{\partial y_i} = \frac{\partial E}{\partial x_j} \cdot \mathbf{w}_{ji}$$

- Now, we have seen how to calculate $\frac{\partial E}{\partial y}$ for any unit in the penultimate layer when given information $\frac{\partial E}{\partial y}$ from the last layer
- This can be iterated backwards such that the derivatives $\frac{\partial E}{\partial w_{ji}}$ become known along the way.
- These are used for (stochastic) gradient descent!

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- It is a very good idea to spell out this for the XOR problem. You can follow the following article (using different names than here)
 - <u>https://medium.com/@14prakash/back-propagation-is-very-simple-who-made-it-complicated-97b794c97e5c</u>
- One way of thinking about back-propagation is that it is a major factorization of the derivative into things that we can calculate as numbers!

$$\frac{dE}{dw} = \frac{dE}{dy} \cdot \frac{dy}{dx} \cdot \frac{dx}{dw}$$



Classical Networks

- Input, a few hidden layers, an output
- Difficulty: expressivity (number of layers) vs. trainability (number of parameters)

Convolutional Neural Networks and Pooling

- Input an image, Layers are now calculating some local convolution of the image and dimensionality is reduced by pooling, that is taking only a subset of the data points.
- Less Weights (only once for the convolution kernel which is swiped over the image, not for every pixel)

Recurrent Networks

 They can have loops. That is the output of a layer serves as the input of a previous layer. Sequences are typical examples, the network can remember (learn to remember)



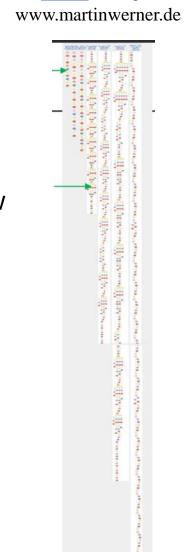
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- Now, Backpropagation can train deep networks and, therefore, XOR,but
 - Not enough processing power (no GPUs, for example)
 - Lack of Datasets (big and annotated datasets, because in realworld scenarios you would need those)
 - Overfitting (mainly, because you need to choose a sufficiently expressive architecture but don't have enough data to train)
 - Vanishing Gradient Problem
 - During learning, you multiply a lot of very small numbers which eventually get too small for sensible learning on finite accuracy machines
- People turned away, because practical examples of deep networks were not brought to significant success, especially as other techniques became very powerful including support vector machines

- Training tricks
- ImageNet Dataset (2009, 16 million annotated images)
- Visibility through ILSVRC (1 million images, 1,000 classes)

2013: AlexNet trained on ImageNet using two GPUs

- Dropout
- Rectified Linear Units (ReLU) instead of sigmoid or tanh activations
- Data Augmentation

- Errors drop significantly year by year
- Architectures get deeper and deeper
 - Trainable with tricks
- Some results from the golden years of CNNs follow







CNN based, non-CNN based

2014 Teams	%error
GoogLeNet	6.6
VGG (Oxford)	7.3
MSRA	8.0
A. Howard	8.1
DeeperVision	9.5
NUS-BST	9.7
TTIC-ECP	10.2
xyz	11.2
UvA	12.1

2012 Teams	%error
Supervision (Toronto)	15.3
ISI (Tokyo)	26.1
VGG (Oxford)	26.9
XRCE/INRIA	27.0
UvA (Amsterdam)	29.6
INRIA/LEAR	33.4

2013 Teams	%error
Clarifai (NYU spinoff)	11.7
NUS (singapore)	12.9
Zeiler-Fergus (NYU)	13.5
A. Howard	13.5
OverFeat (NYU)	14.1
UvA (Amsterdam)	14.2
Adobe	15.2
VGG (Oxford)	15.2
VGG (Oxford)	23.0



- In 2015, Microsoft Research Asia won with a 150 layer network
 - Almost superhuman performance (3.5 % error, later even improved)
- GoogLeNet 2014 had 22 layers
- Is the next AI winter just around the corner?
 - We have been successful in image regognition, speech, and translation.
 - But we rely on excessive datasets that we cannot generate
 - By abuse of language (AI vs. ML) also termed "narrow AI"



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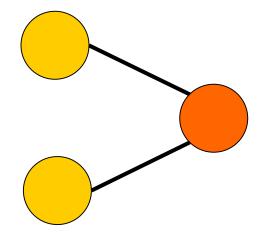


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Some Basic Deep Learning Architectures

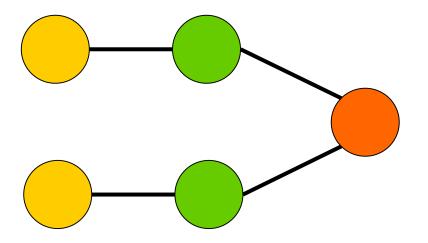


Perceptron (P)



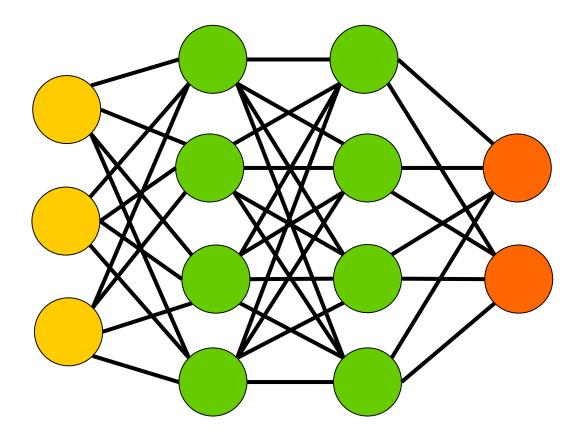


Feed Forward (FF)

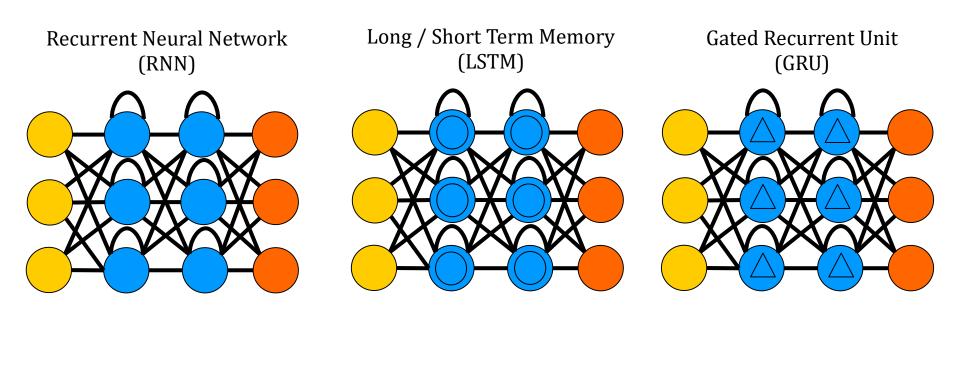




Deep Feed Forward (DFF)

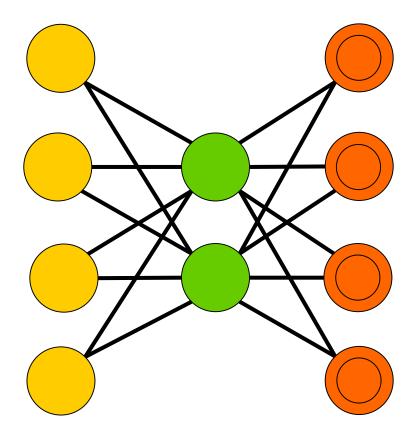


Architectures



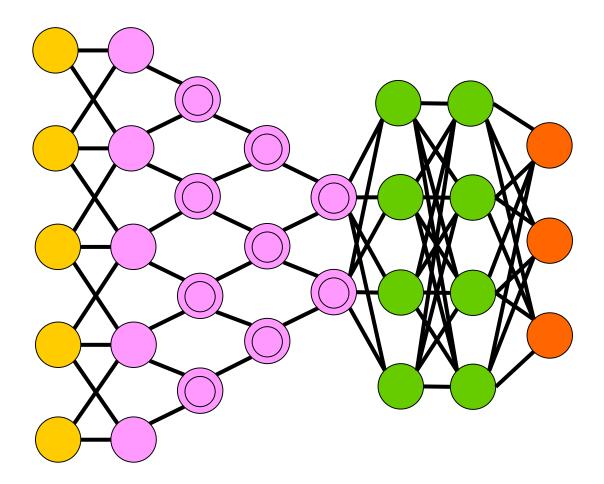


Auto Encoder (AE)



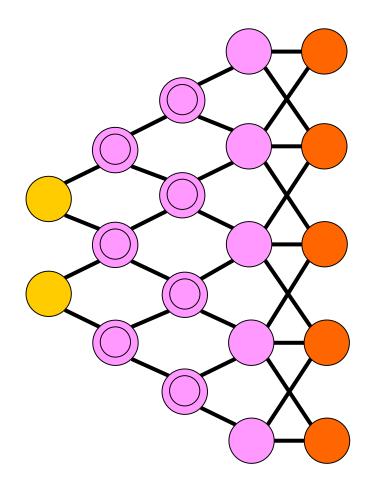


Deep Convolutional Network (CNN)



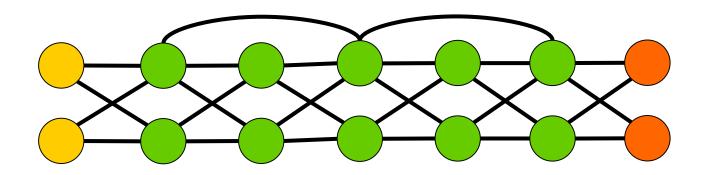


Deconvolutional Network (DN)





Deep Residual Network (DRN)





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Dealing with Point Clouds





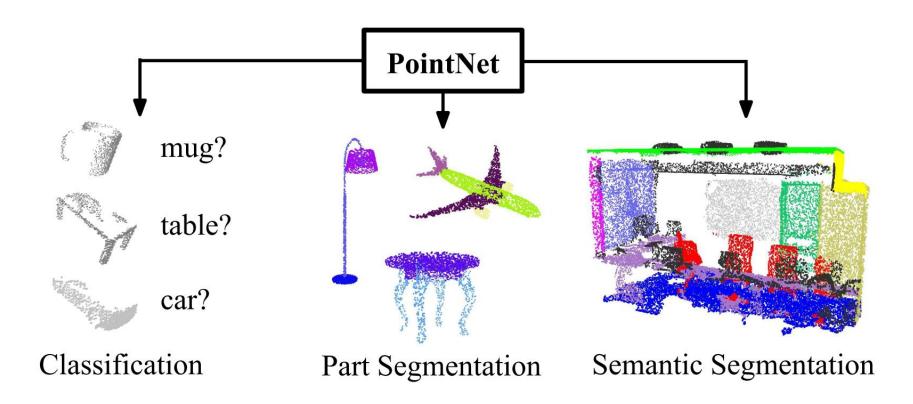
This CVPR paper is the Open Access version, provided by the Computer Vision Foundation. Except for this watermark, it is identical to the version available on IEEE Xplore.

PointNet: Deep Learning on Point Sets for 3D Classification and Segmentation

Charles R. Qi*

Hao Su* Kaichun Mo Stanford University Leonidas J. Guibas

Why?





- Should be invariant for certain transformations
- Can be global or local
- Usually need a context definition (for pure 3D points)
- Including Deep Feed-Forward Architectures!
- Volumetric CNNs
 - Step towards a voxelgrid and use (learned) 3D convolutions

Multiview CNNs

- Render several perspective views of the point clouds and feed them to a CNN
- Limited to aspects represented by 2D aspects (e.g., classification, but not completion)



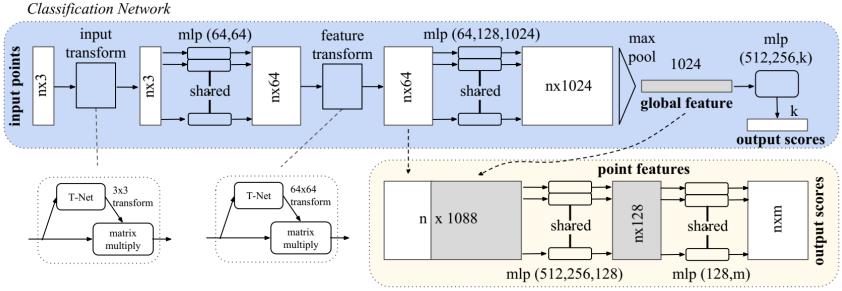


- Point Clouds are Unordered Collections of Points
 - and there is no sensible ordering function

Model Functionalities Needed

- Classification outputs a score for each candidate class
- For Scene Understanding / Segmentation, the model outputs scores for each point and each candidate class





Segmentation Network



- Based on three main properties, assertions and their consequences
 - The order of the points shall not matter
 - Nearby things shall be able to interact with each other
 - The system should become invariant under rigid transformation including rotation, translation, and flip



- To make a model invariant under the order of input points can be done basically in three ways:
 - Sort input into a canonical order,
 - However, no order exists that preserves data locality completely
 - Treat the input as a sequence and train with all permutations of the input
 - However, it has been shown that order matters still.
 - Excessive training times (There are n! permutations)
 - Use a simple, symmetric function to aggregate information from each point
 - Okay, lets go for it...

It would be easy to use addition or mul-commutative. But more flexibility is nee (learnable) function is preferred.

$$f(\{x_1,\ldots,x_n\}) \approx g(h(x_1),\ldots,h(x_n)), \qquad (1)$$

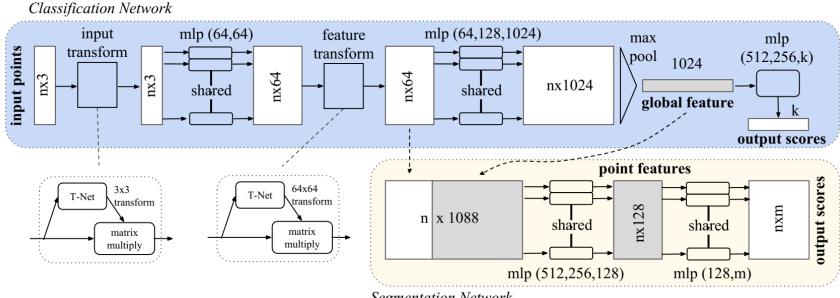
where
$$f : 2^{\mathbb{R}^N} \to \mathbb{R}, h : \mathbb{R}^N \to \mathbb{R}^K$$
 and $g : \mathbb{R}^K \times \cdots \times \mathbb{R}^K \to \mathbb{R}$ is a symmetric function.

- Therefore, f is a function mapping the point cloud to a single real number (e.g., a point feature)
- But it is being factorized into a function g representing max-pooling and h representing multilayer perceptron networks.
- Several functions h lead to several features now independent from the point set ordering

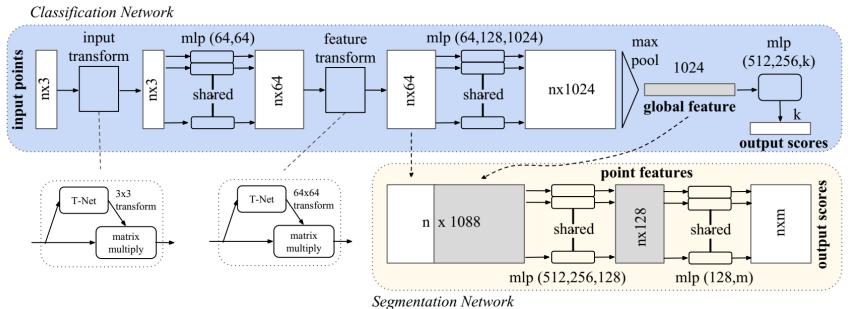




- For now, we just transformed the **whole point cloud** into a **single** feature vector $f_1 \dots f_k$
 - We can now just train any machine learning system like a SVM or a MLP on this very result
 - However, this can only rely on **global information**
- But, we will need a combination of local and global information
- This is done in the **Segmentation Network**







- It concatenates 64 per point features with 1024 global features for a matrix of nx1088 of features
 - Thus, it can use local and global informamtion
 - Experimentally shown that, for example, normals can be predicted from this stage



- The remaining piece is how to achieve invariance under rotation, translation etc.
- Idea: Predict an affine transformation matrix (T-Net) and apply this transformation to the input points
 - These mini-networks have the same structure as the global network: point independent feature extraction, max pooling, and fully connected layers
- This can as well be applied again to the feature space.
 - But beware, it is a large matrix and difficult to optimize
 - Therefore, a constraint makes it almost orthogonal by adding to the loss

$$L_{reg} = \|I - AA^T\|_F^2,$$

Why PointNet? Because it looks nice and works in practice



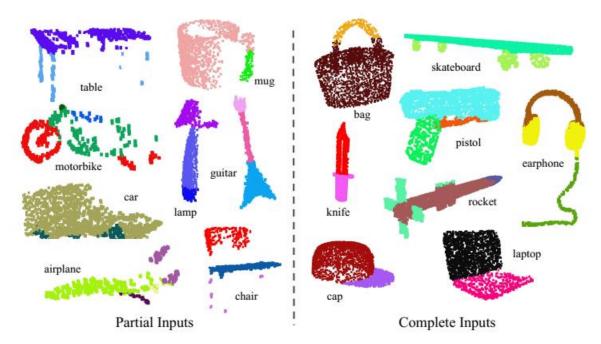


Figure 3. **Qualitative results for part segmentation.** We visualize the CAD part segmentation results across all 16 object categories. We show both results for partial simulated Kinect scans (left block) and complete ShapeNet CAD models (right block).







Theorem 1 Suppose $f : \mathcal{X} \to \mathbb{R}$ is a continuous set function w.r.t Hausdorff distance $d_H(\cdot, \cdot)$. $\forall \epsilon > 0$, \exists a continuous function h and a symmetric function $g(x_1, \ldots, x_n) = \gamma \circ MAX$, such that for any $S \in \mathcal{X}$,

$$\left| f(S) - \gamma \left(\max_{x_i \in S} \left\{ h(x_i) \right\} \right) \right| < \epsilon$$

where x_1, \ldots, x_n is the full list of elements in S ordered arbitrarily, γ is a continuous function, and MAX is a vector max operator that takes n vectors as input and returns a new vector of the element-wise maximum.

Funktionen h und g existieren also tatsächlich für jede Fehlerschranke. Allerdings ist das kein Ergebnis zur Trainierbarkeit. Nur die Existenz...



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PointNet++

51



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- PointNet uses a single Max-Pooling layer, which means that all features are single-scale
 - Point Clouds have varying sampling density, especially with fixed sensors
- PointNet++ is based on a hierarchical grouping analyzing larger and larger extracts of the point cloud
 - Implemented as Compression: At each and every step, a point set is abstracted to a point set with fewer points
 - Three "layers":
 - **Sampling**, selects a set of points as centroids
 - **Grouping**, assigns points to centroids
 - PointNet++ uses a "mini"-PointNet to extract features



- Sampling Layer
 - Iterative Farthest Point Sampling (FPS)
 Iteratively add the farthest point from the input to the current set
- Grouping Layer
 - Assign some neighboring points using a
 - ball query
 - Pro: same scale, Con: different number of elements
 - kNN
 - Pro: same number of elements, Con: different scale
 - Ball query preferred as PointNet can deal with varying inputs
- Many additional tricks
 - See <u>https://arxiv.org/pdf/1706.02413.pdf</u>



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And now? How would I?



- Run a computer / container with tensorflow
 - I am running NVIDIA's optimized tensorflow container (need an account at NVIDIA container registry)
 - Optimized by NVIDIA for DGX-1 Familiy
 - On 8 interconnected V100 GPUs (256 GB total memory)
 - Trains about 2 hours to 88.8 % accuracy on point cloud classification for ModelNet 40 dataset
- Inside the container (or in the Dockerfile)
 - apt-get install libhdf5-dev (for HDF5 file support)
 - pip install h5py
 - git clone https://github.com/charlesq34/pointnet
 - python train.py
 - Automatically downloads dataset
 - Runs a few epoochs and outputs results

```
root@ede2a32eccac:/workspace/pointnet# python train.py
--2019-01-17 06:41:18--
https://shapenet.cs.stanford.edu/media/modelnet40 ply hdf5
2048.zip
Resolving shapenet.cs.stanford.edu
(shapenet.cs.stanford.edu)...
171.67.77.19
Connecting to shapenet.cs.stanford.edu
(shapenet.cs.stanford.edu)|171.67.77.19|:443... connected.
HTTP request sent, awaiting response... 200 OK
Length: 435212151 (415M) [application/zip] Saving to:
`modelnet40_ply_hdf5_2048.zip'
```

modelnet40_ply_hdf5 100%[============>] 415.05M
310KB/s in 22m 30s



```
[...]
eval mean loss: 0.549058
eval accuracy: 0.886769
eval avg class acc: 0.860618
**** EPOCH 249 ****
[...]
----1----
eval mean loss: 0.546670
eval accuracy: 0.888393
eval avg class acc: 0.858817
```

(after 2 hours including data download on a single DGX-1)

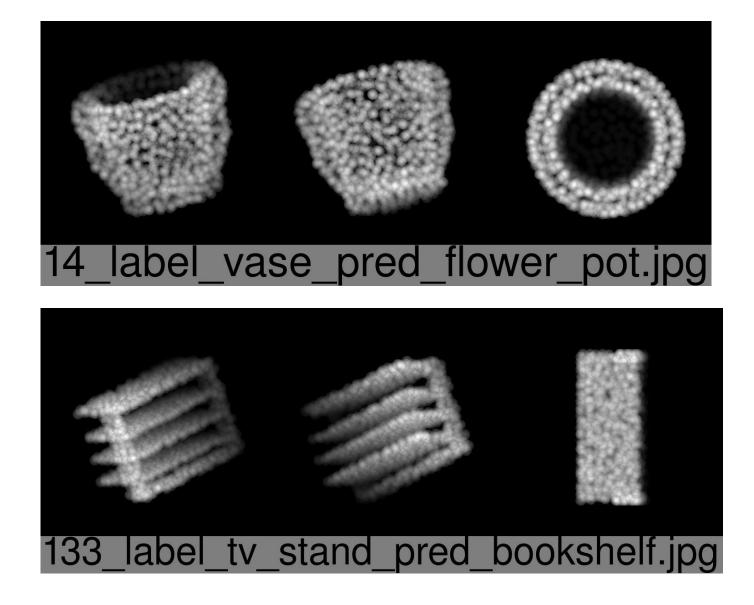


```
$> pip install scipy
$> pip install image # for PIL
$> pip install matplotlib # for visualizations
$> python evaluate.py -visu
```

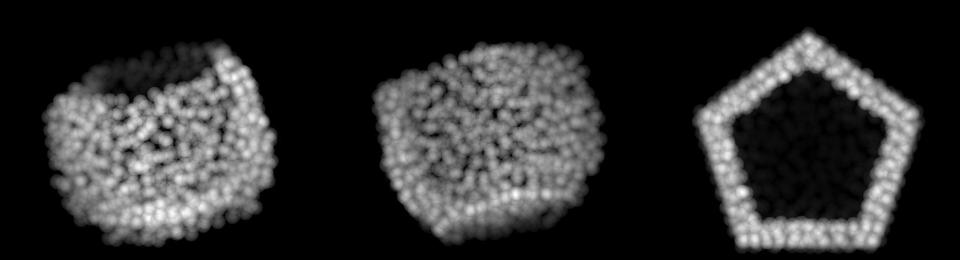
This now creates output of erroneous classifications in the dump folder and gives per class performance results. Looks like

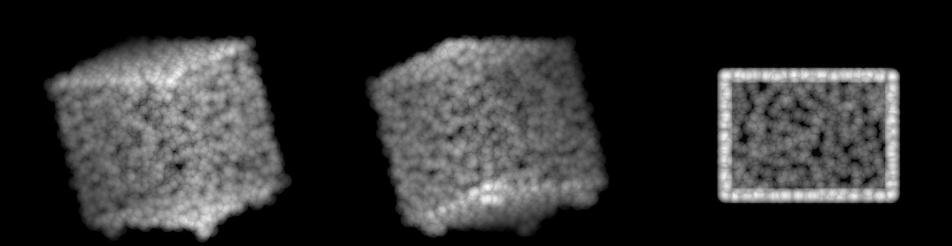
airplane:	1.000
bathtub:	0.860
bed:	0.980
bench:	0.700
bookshelf:	0.900
bottle:	0.940
bowl:	0.950
car:	0.990
chair:	0.980
cone:	0.950
cup:	0.550



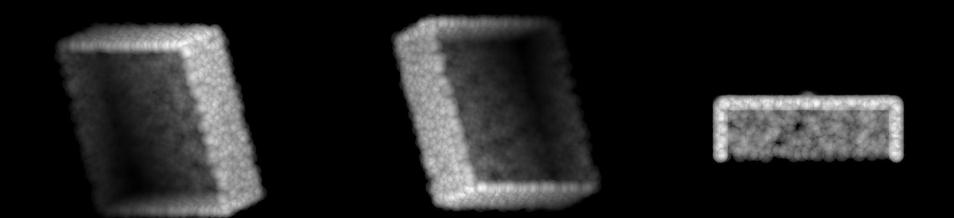


0_label_vase_pred_cup.jpg





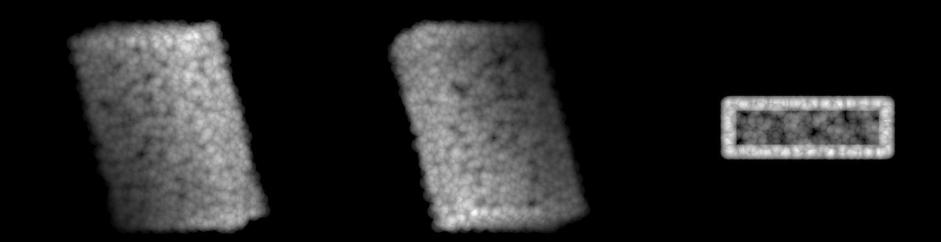
1_label_dresser_pred_night_stand.jpg



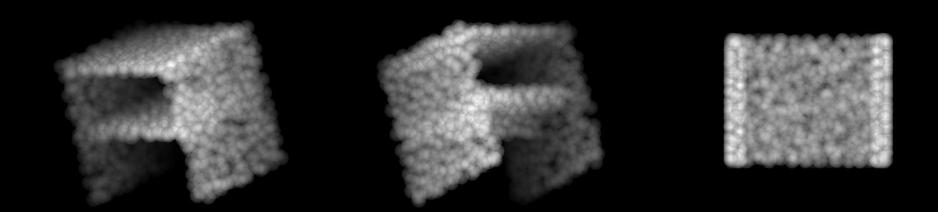
2_label_wardrobe_pred_mantel.jpg

3_label_table_pred_desk.jpg

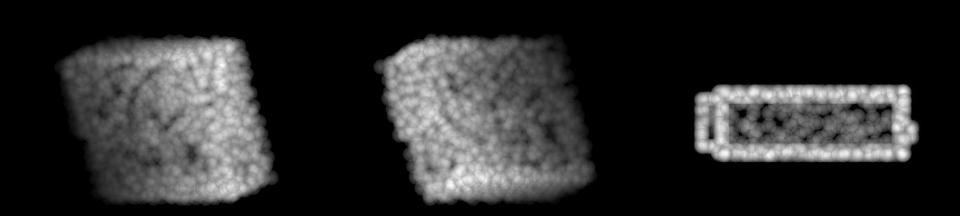




4_label_wardrobe_pred_xbox.jpg



5_label_night_stand_pred_table.jpg

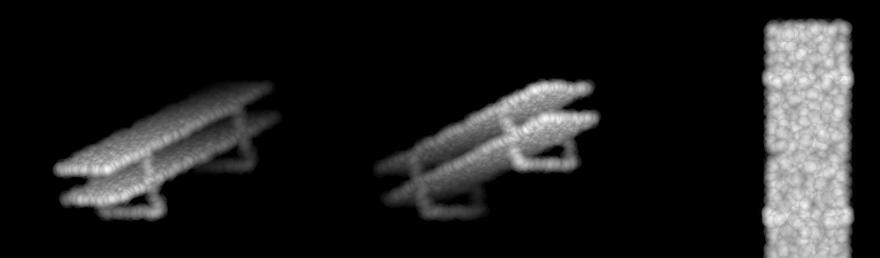


6_label_xbox_pred_wardrobe.jpg

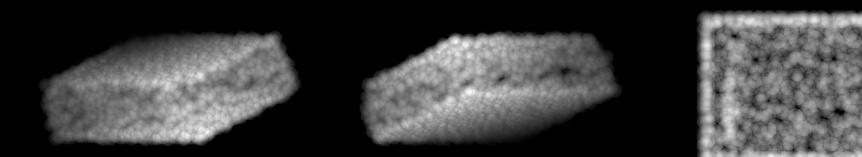
7_label_plant_pred_lamp.jpg



8_label_tv_stand_pred_table.jpg



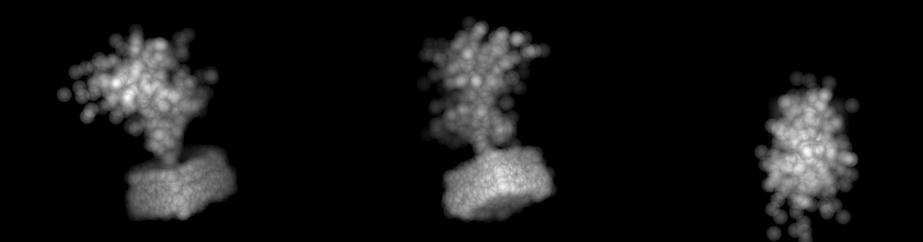
9_label_bed_pred_radio.jpg

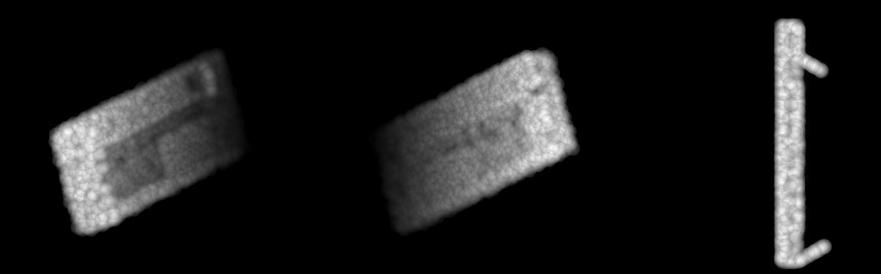




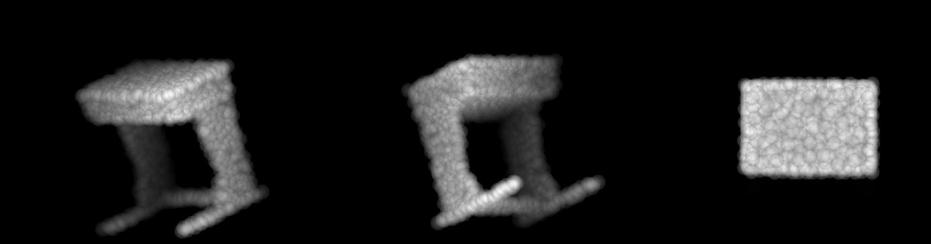
10_label_flower_pot_pred_plant.jpg





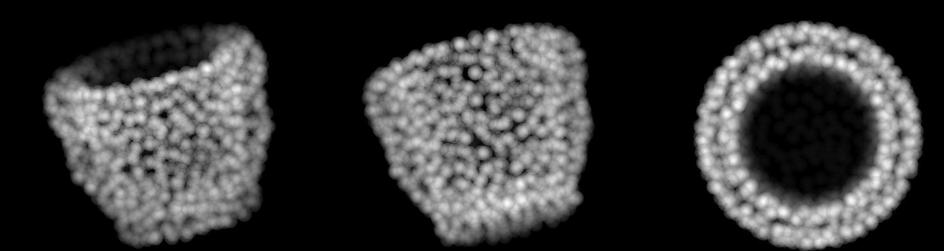


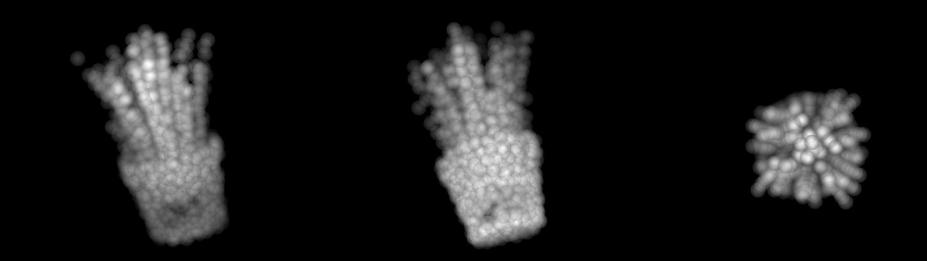
12_label_tv_stand_pred_wardrobe.jpg



13_label_desk_pred_table.jpg



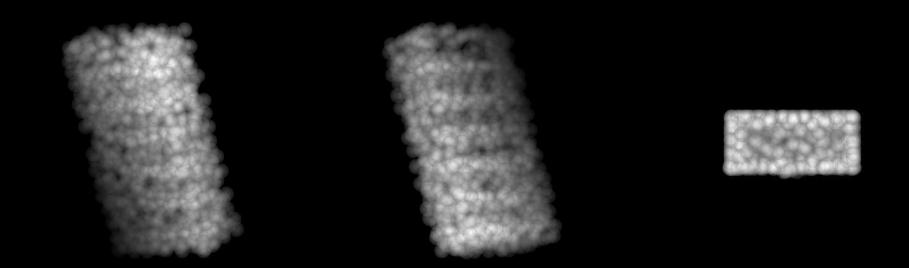




15_label_plant_pred_flower_pot.jpg



16_label_flower_pot_pred_plant.jpg

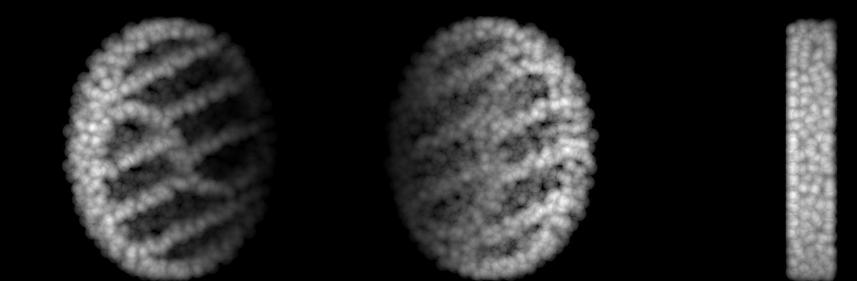


17_label_dresser_pred_bookshelf.jpg

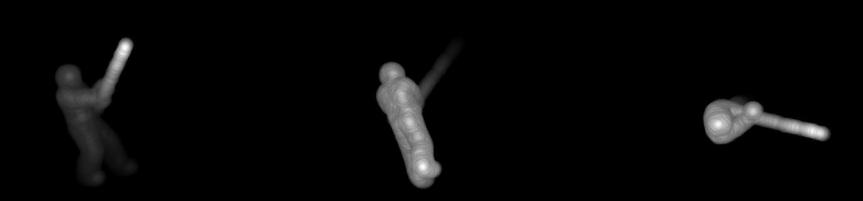


18_label_bathtub_pred_table.jpg

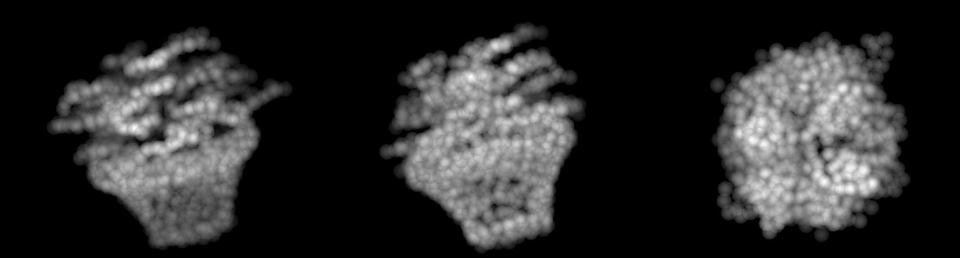
19_label_bookshelf_pred_plant.jpg



20_label_person_pred_plant.jpg



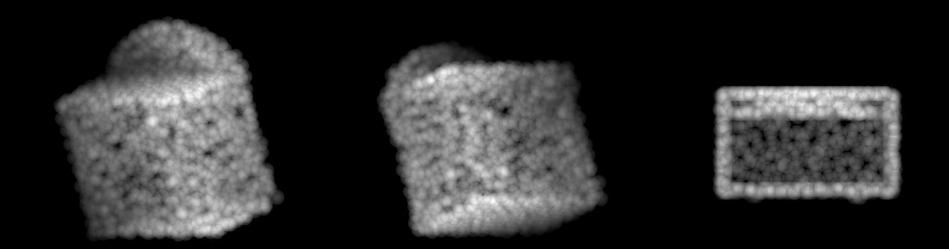
21_label_bookshelf_pred_door.jpg



22_label_plant_pred_flower_pot.jpg

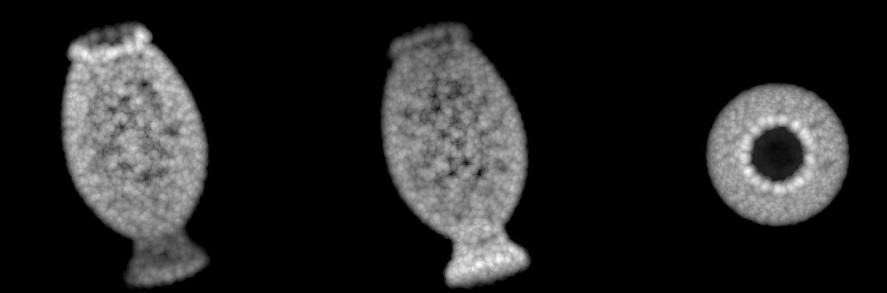
23_label_night_stand_pred_stool.jpg

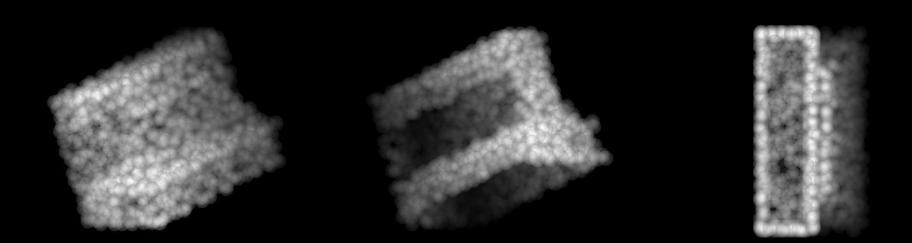




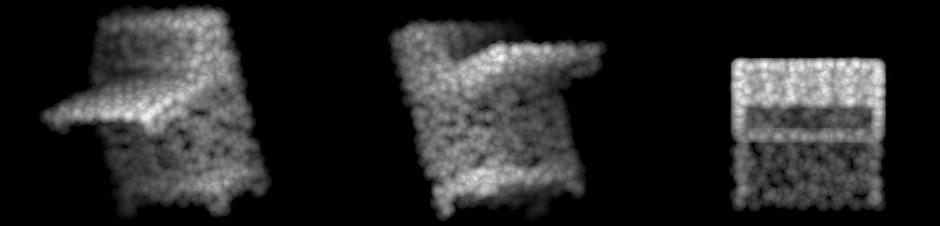
24_label_dresser_pred_sink.jpg

25_label_flower_pot_pred_vase.jpg

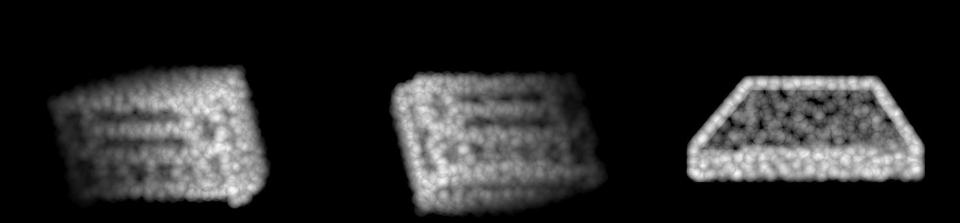




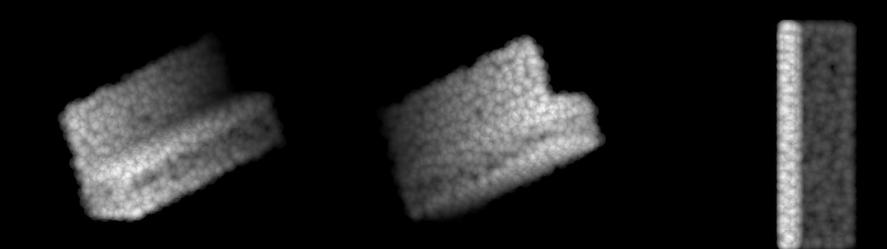
26_label_range_hood_pred_mantel.jpg



27_label_dresser_pred_desk.jpg

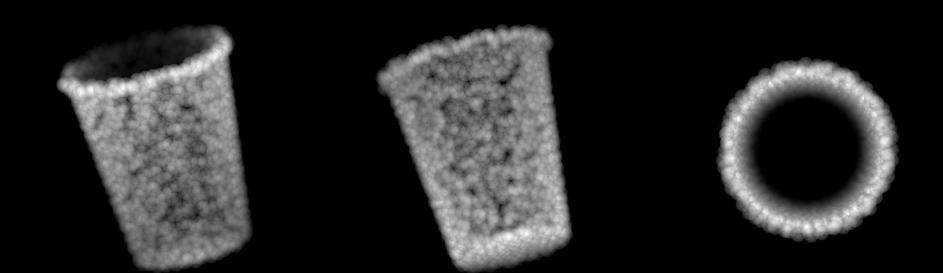


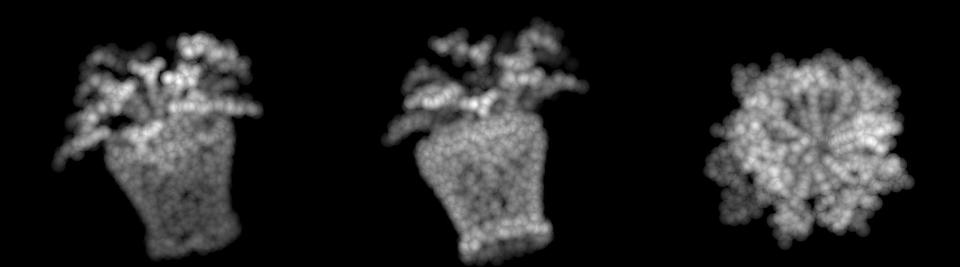
28_label_tv_stand_pred_bookshelf.jpg



29_label_bench_pred_sofa.jpg



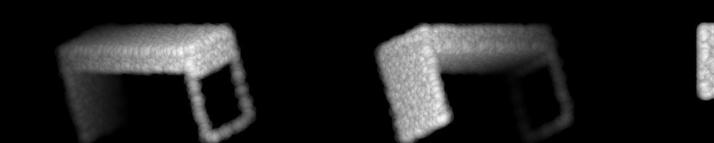




31_label_flower_pot_pred_plant.jpg

32_label_bookshelf_pred_door.jpg

33_label_table_pred_desk.jpg

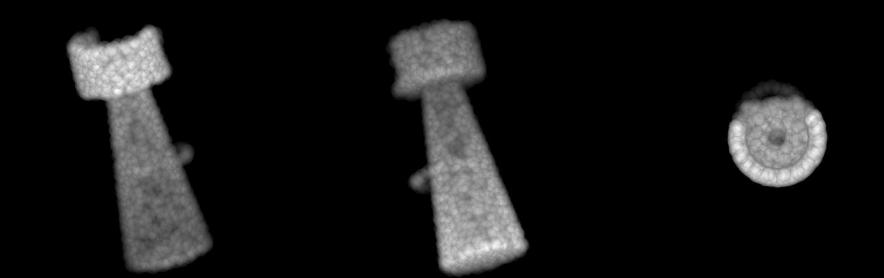


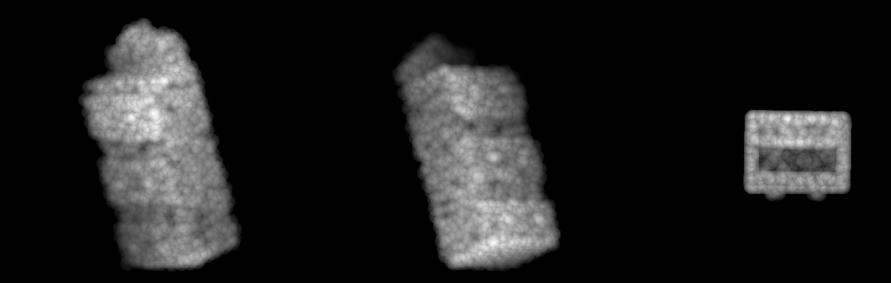




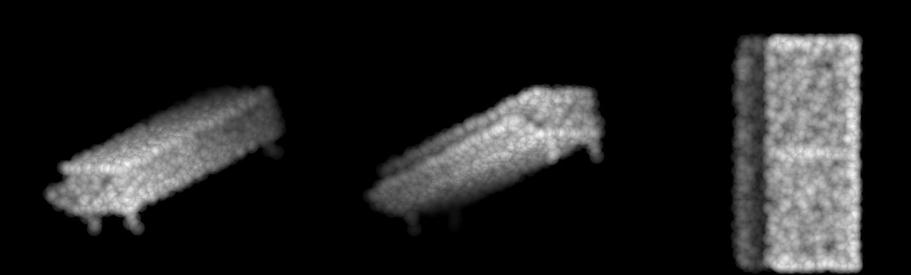


35_label_stool_pred_vase.jpg



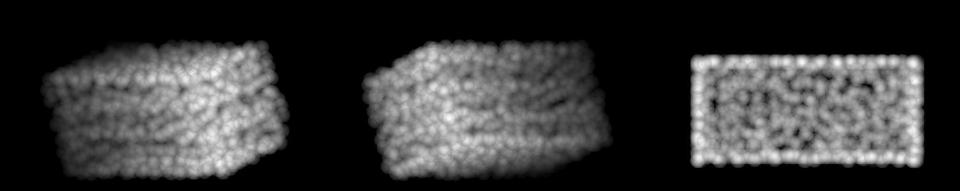


36_label_dresser_pred_bottle.jpg

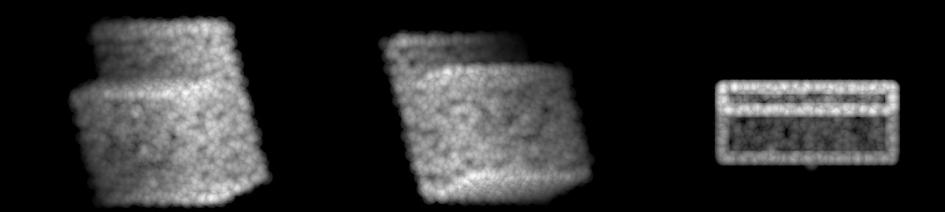


37_label_tv_stand_pred_bench.jpg

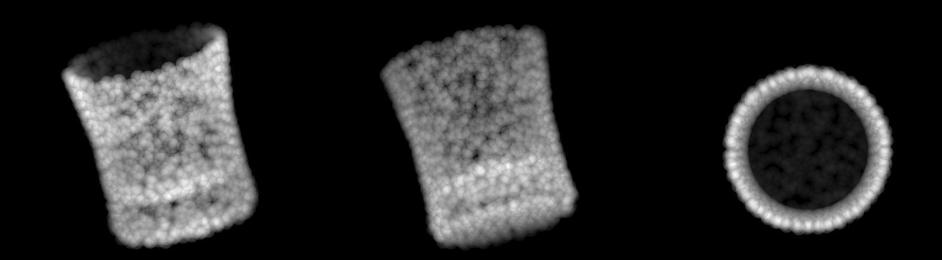


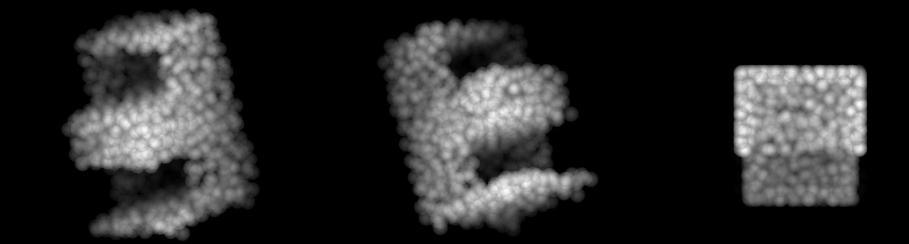


39_label_dresser_pred_sink.jpg

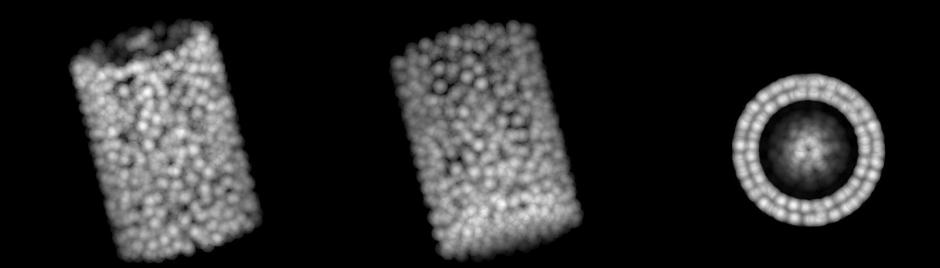


40_label_vase_pred_cup.jpg

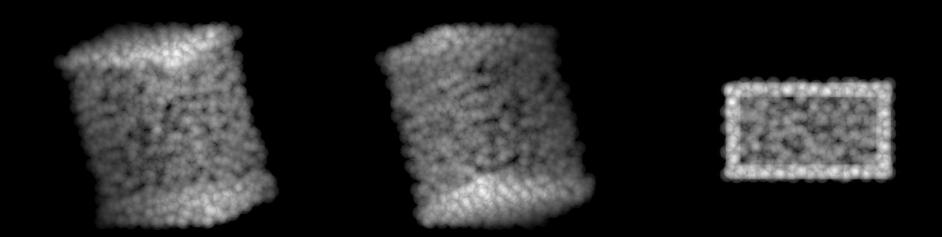




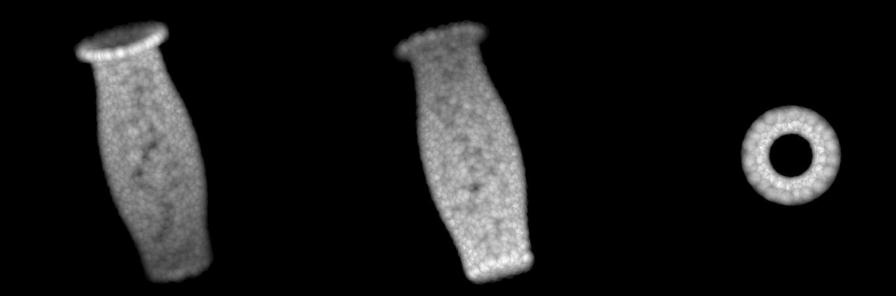
41_label_night_stand_pred_bookshelf.jpg



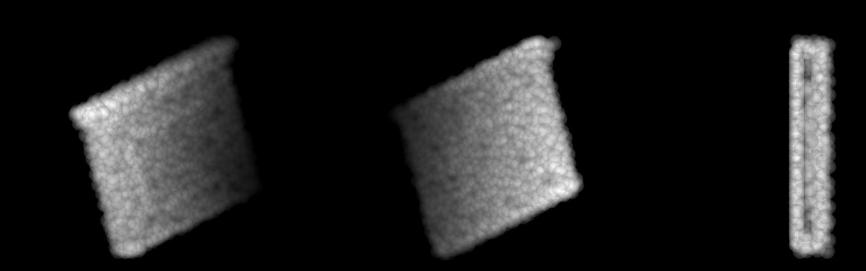
42_label_cup_pred_bottle.jpg



43_label_dresser_pred_wardrobe.jpg

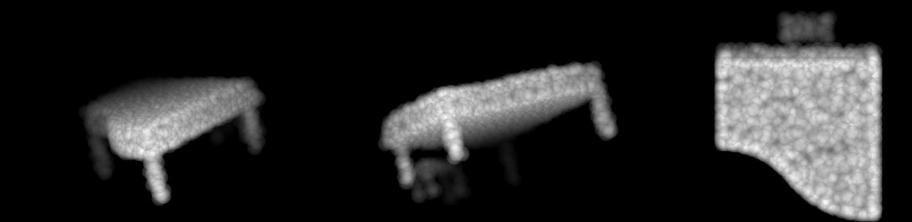


44_label_flower_pot_pred_vase.jpg



45_label_mantel_pred_wardrobe.jpg

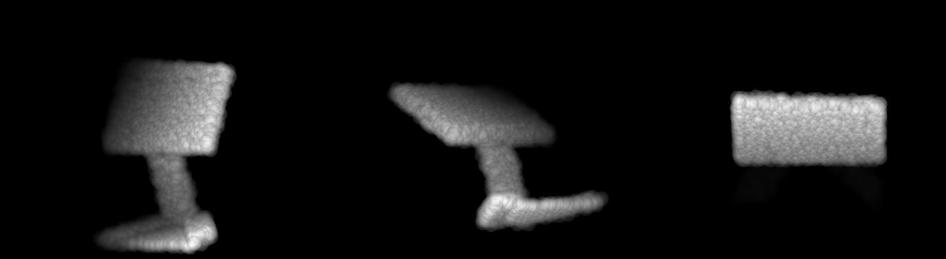






48_label_plant_pred_lamp.jpg



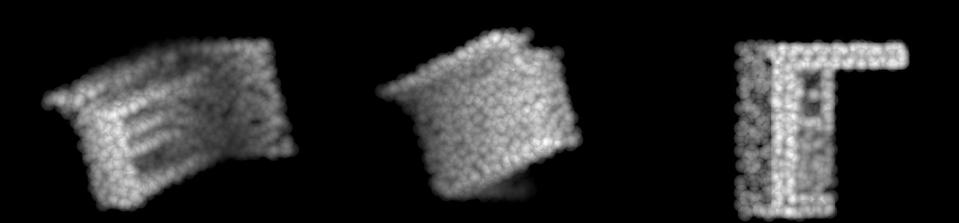


49_label_monitor_pred_stairs.jpg

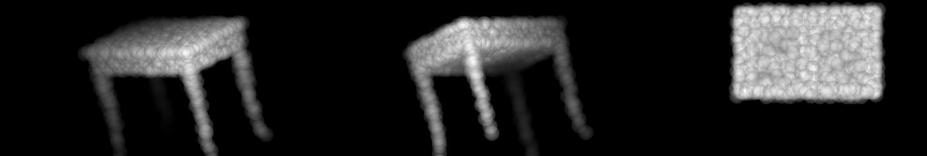
50_label_tent_pred_sofa.jpg

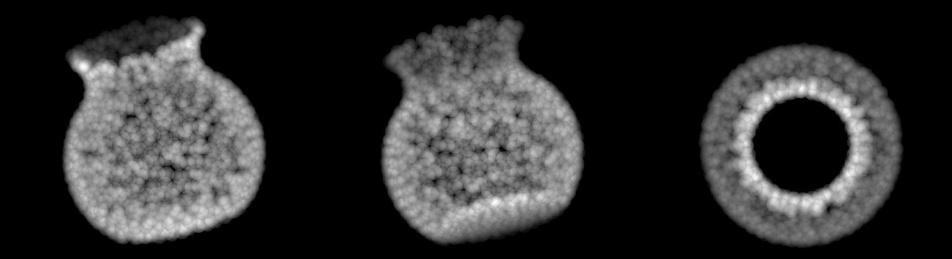


51_label_sink_pred_desk.jpg



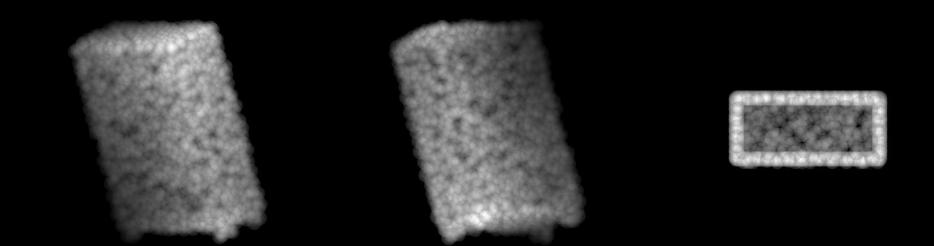
52_label_desk_pred_table.jpg

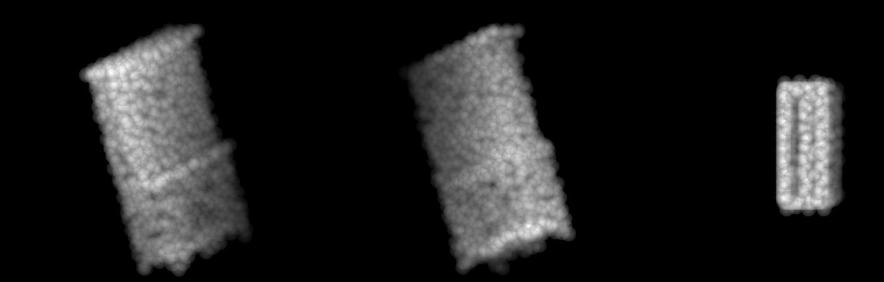




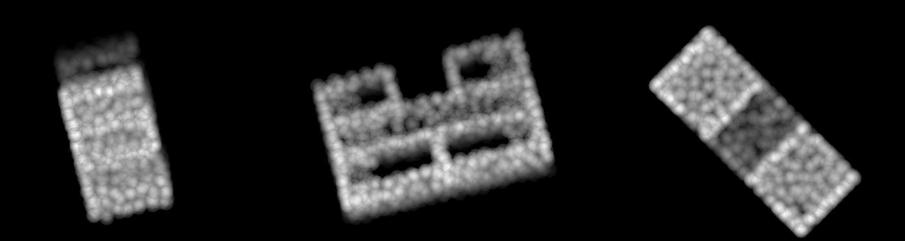
53_label_flower_pot_pred_vase.jpg





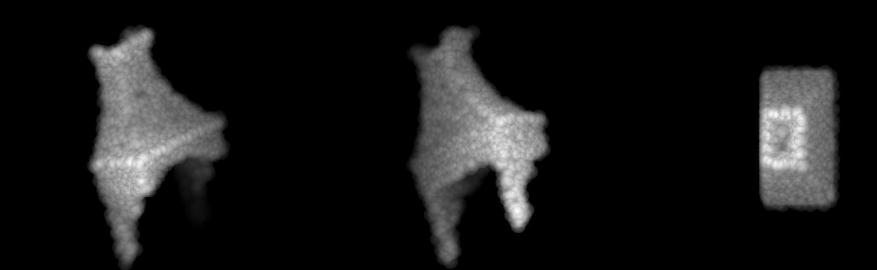


55_label_bookshelf_pred_wardrobe.jpg



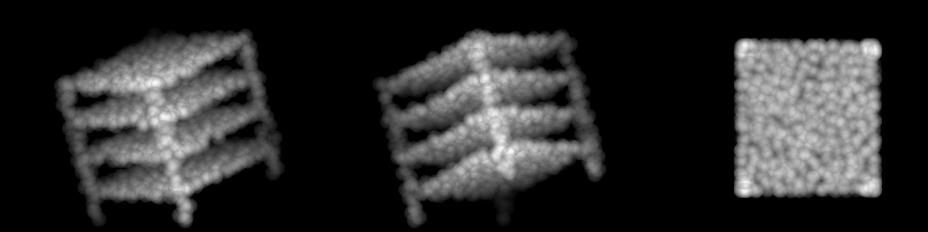
56_label_tv_stand_pred_bookshelf.jpg

57_label_range_hood_pred_mantel.jpg

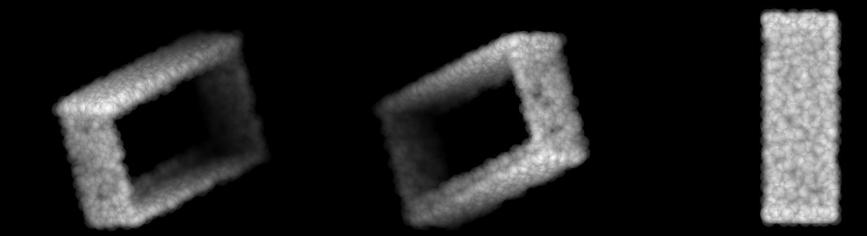




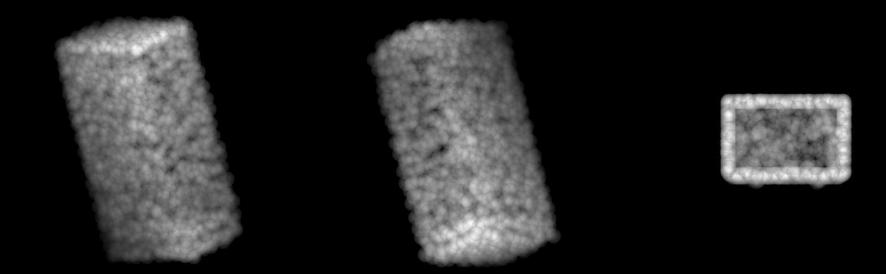
58_label_bookshelf_pred_bottle.jpg



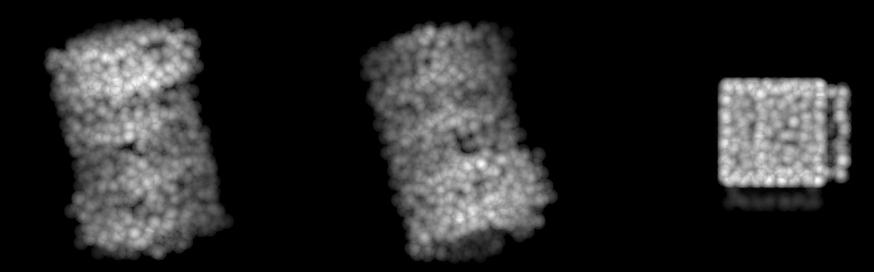
59_label_tv_stand_pred_night_stand.jpg



60_label_tv_stand_pred_table.jpg



61_label_dresser_pred_wardrobe.jpg

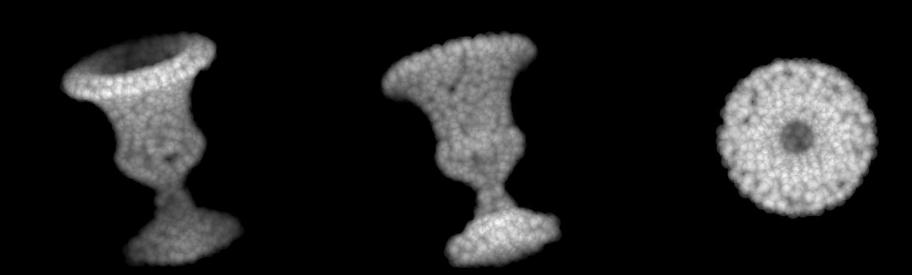


62_label_dresser_pred_bookshelf.jpg

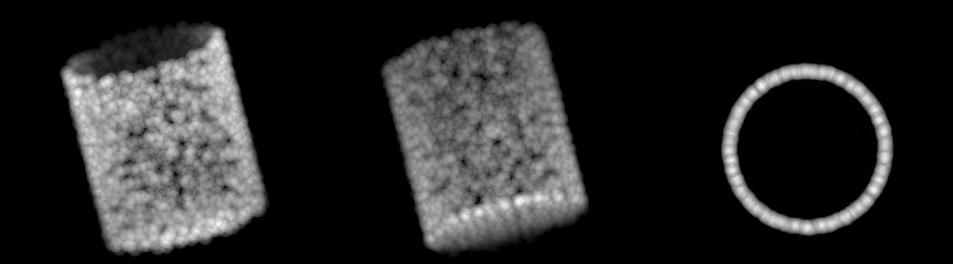


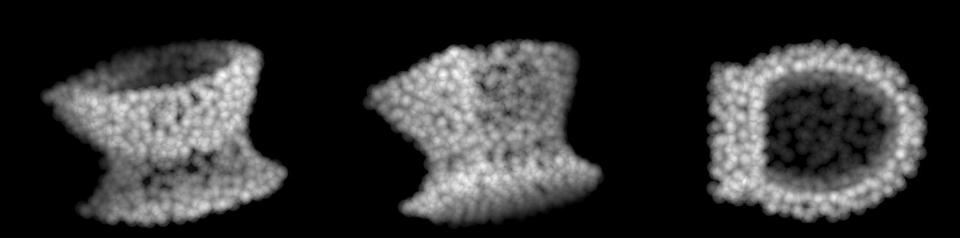




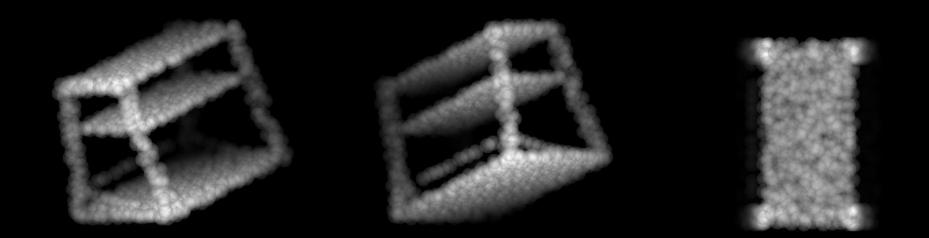


65_label_vase_pred_cup.jpg





66_label_toilet_pred_vase.jpg

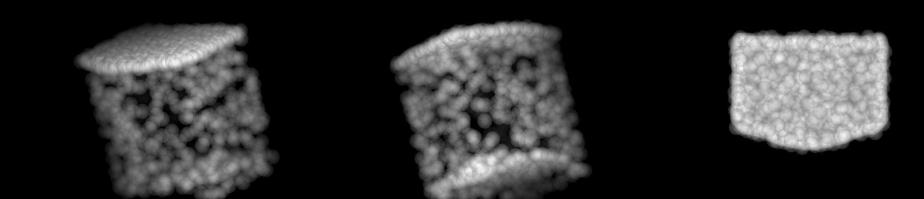


67_label_tv_stand_pred_night_stand.jpg

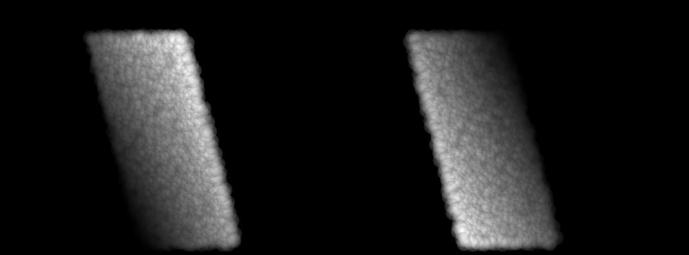
68_label_table_pred_desk.jpg



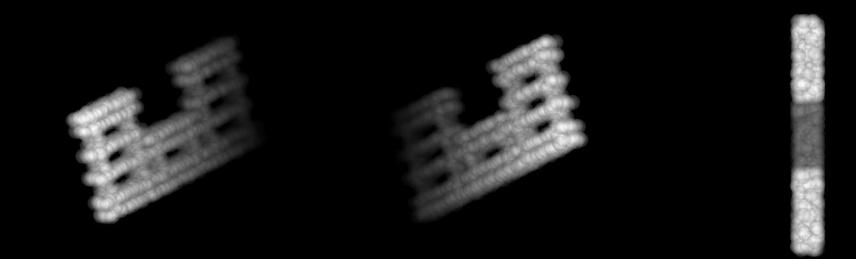
69_label_dresser_pred_night_stand.jpg





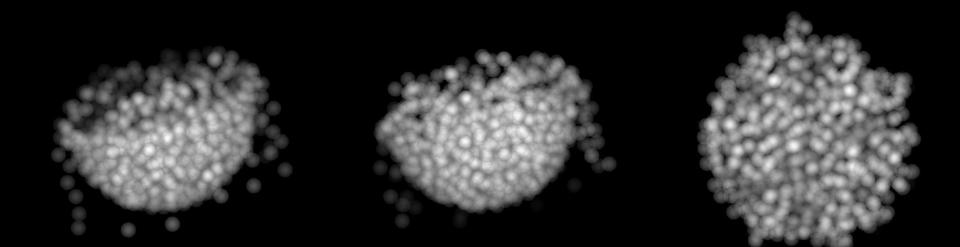


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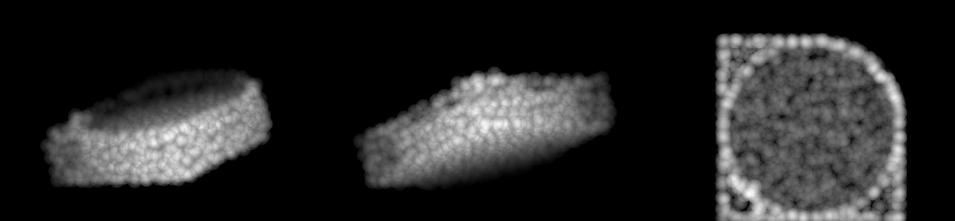
71_label_bookshelf_pred_tv_stand.jpg







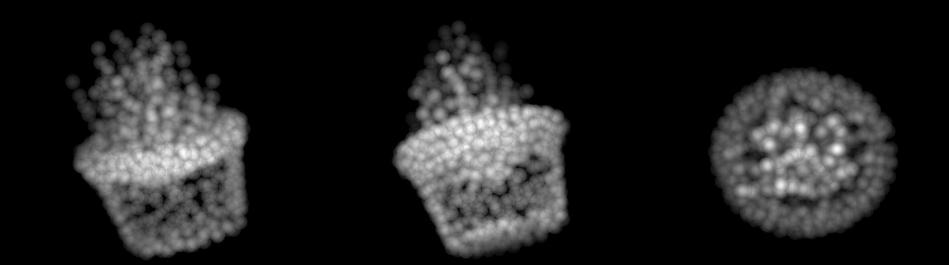




74_label_bathtub_pred_bed.jpg



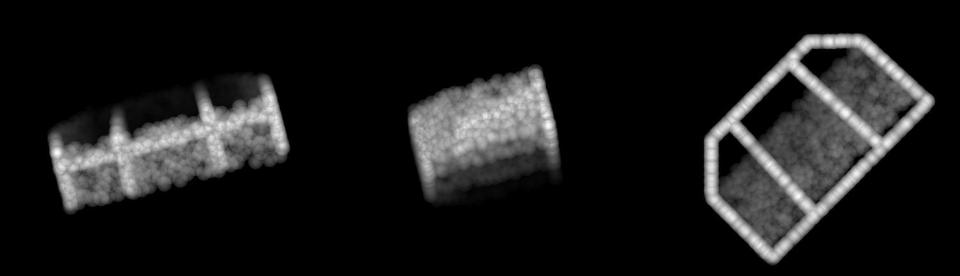
75_label_sofa_pred_bench.jpg



76_label_plant_pred_flower_pot.jpg

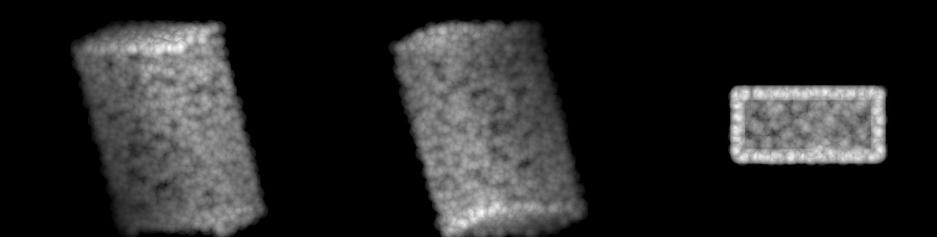


77_label_radio_pred_mantel.jpg

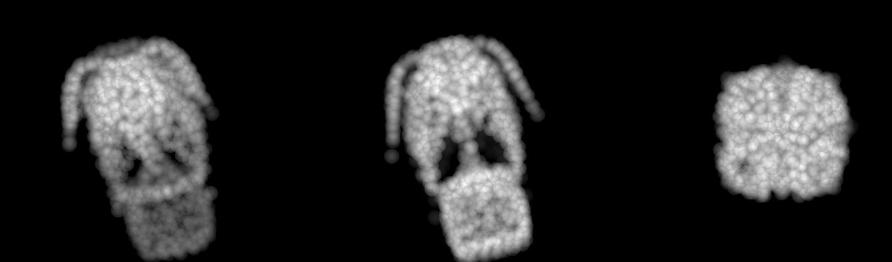


78_label_tv_stand_pred_glass_box.jpg

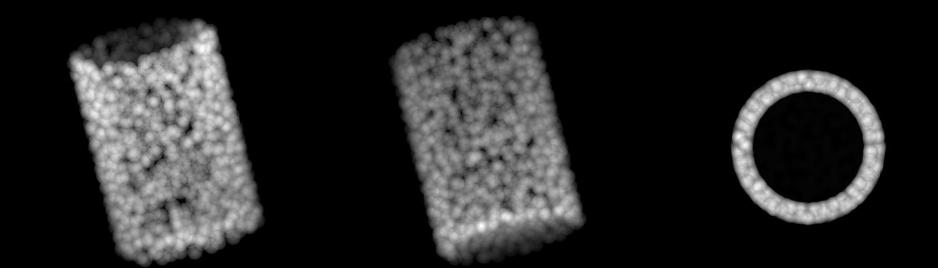




80_label_plant_pred_flower_pot.jpg

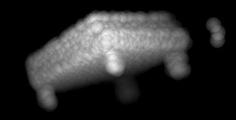


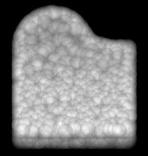
81_label_vase_pred_cup.jpg

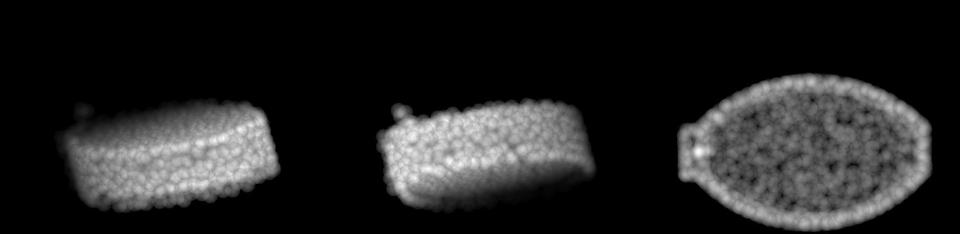


82_label_piano_pred_table.jpg



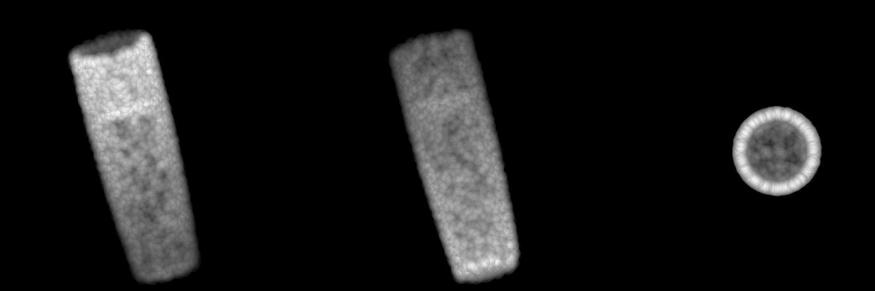




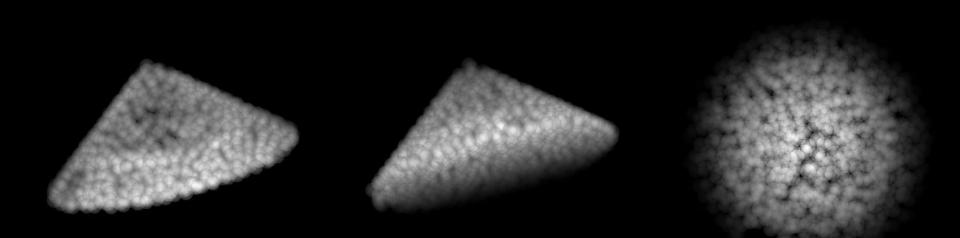


83_label_bathtub_pred_bed.jpg

84_label_vase_pred_cup.jpg

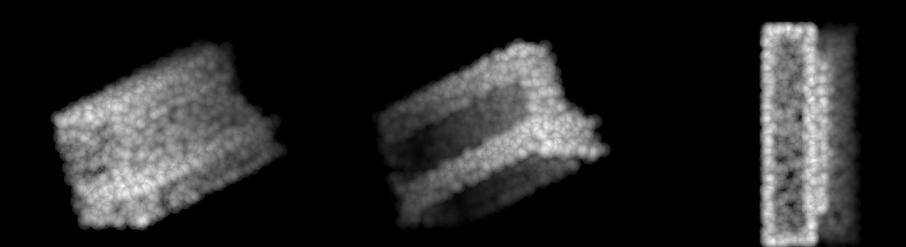


85_label_cone_pred_tent.jpg



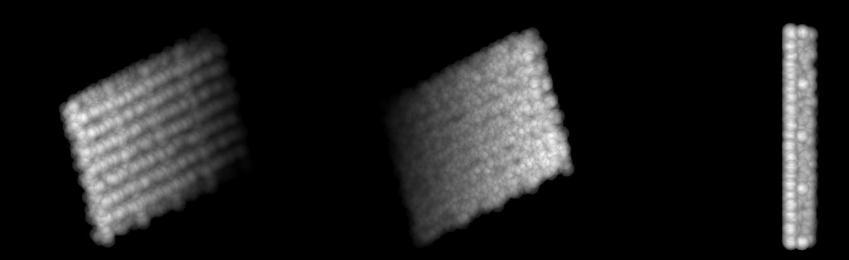




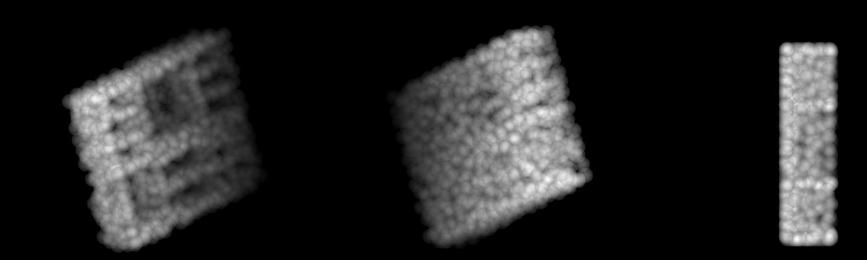




88_label_bathtub_pred_bowl.jpg



89_label_bookshelf_pred_monitor.jpg



90_label_wardrobe_pred_bookshelf.jpg



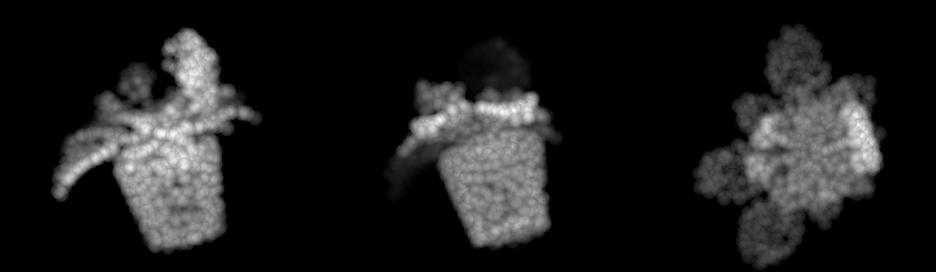


92_label_piano_pred_table.jpg





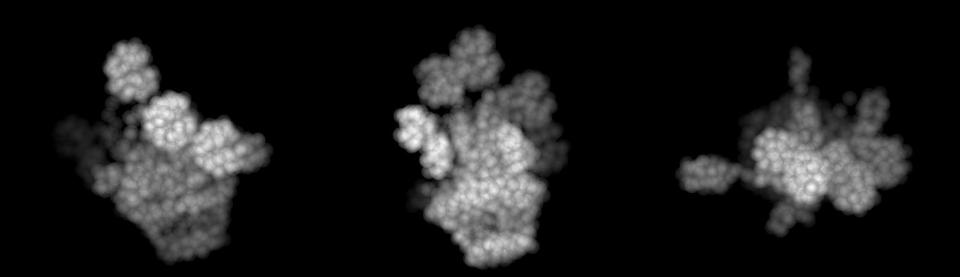




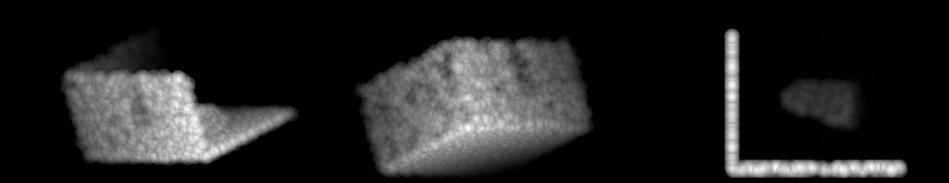
94_label_plant_pred_flower_pot.jpg





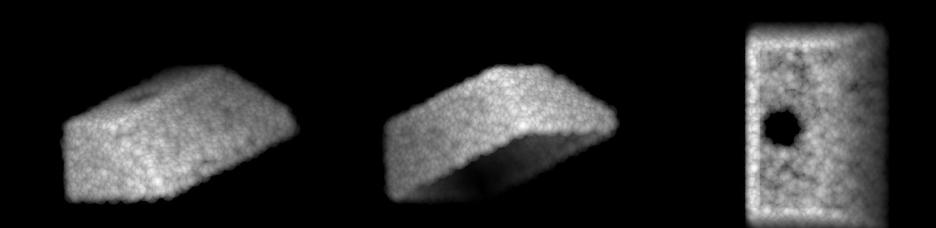


96_label_plant_pred_flower_pot.jpg

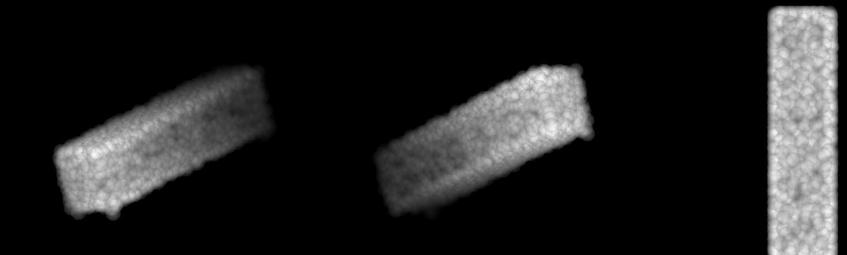


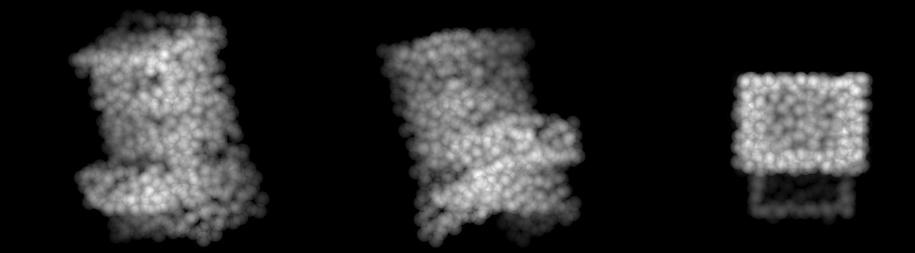
97_label_piano_pred_laptop.jpg





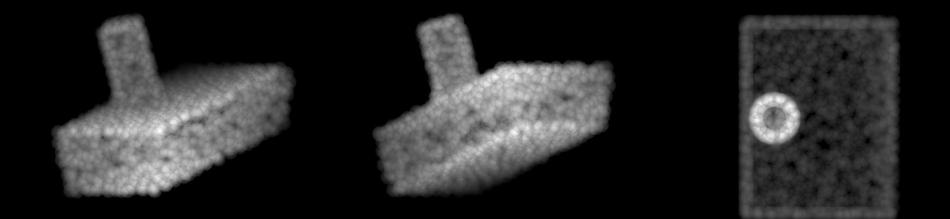


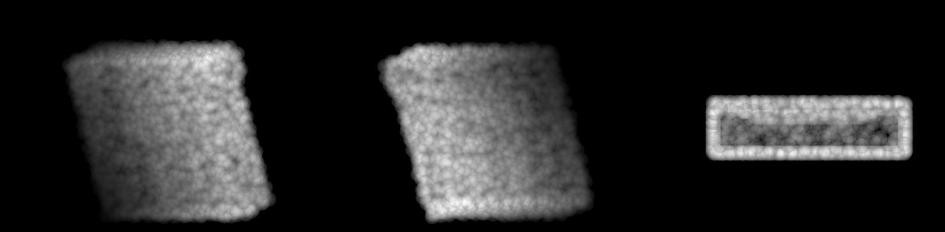




100_label_night_stand_pred_dresser.jpg

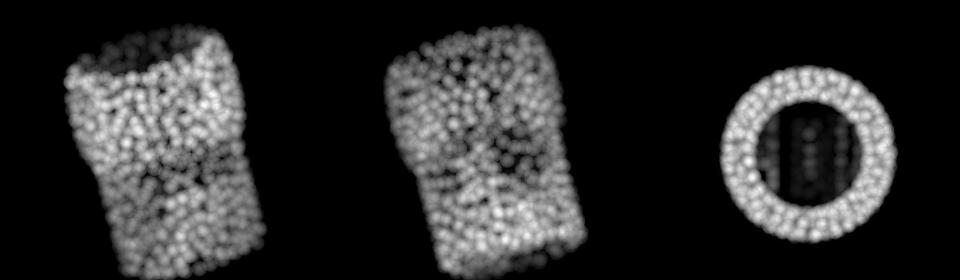
101_label_range_hood_pred_tent.jpg



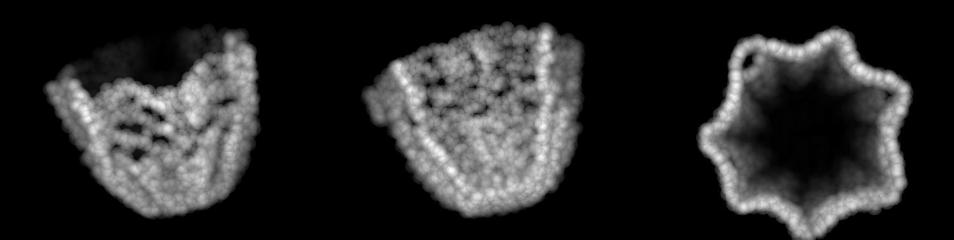


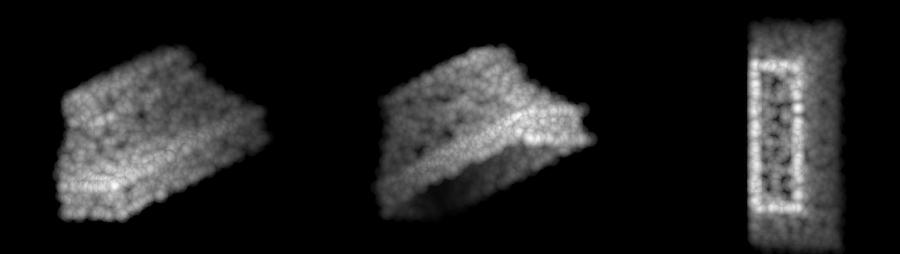
102_label_mantel_pred_xbox.jpg

103_label_cup_pred_vase.jpg



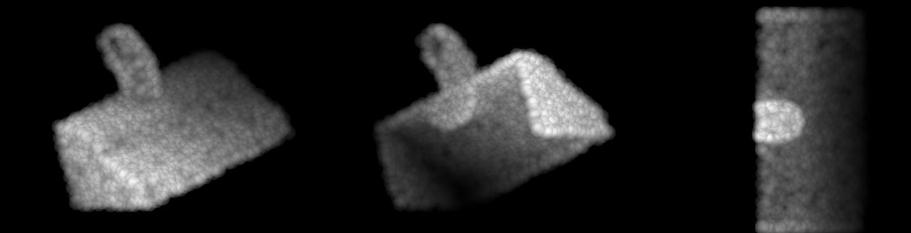




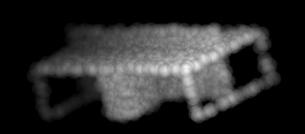


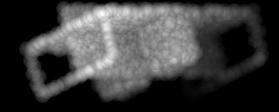
105_label_range_hood_pred_mantel.jpg

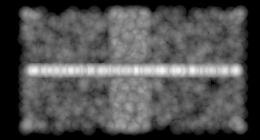


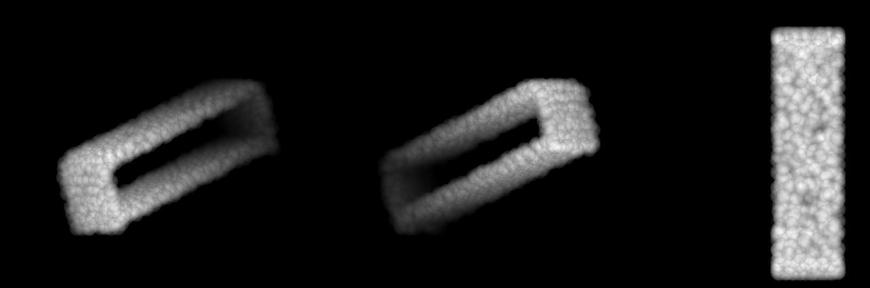


107_label_desk_pred_sofa.jpg



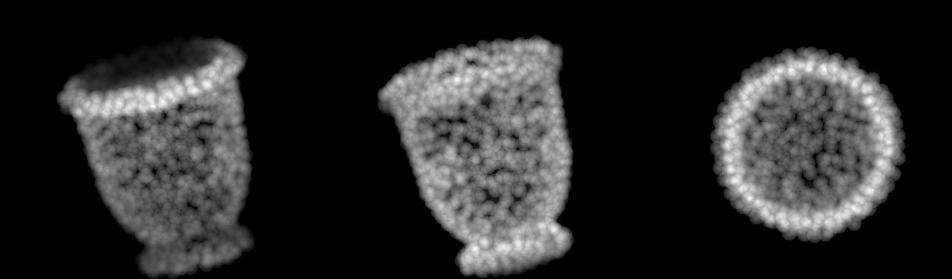


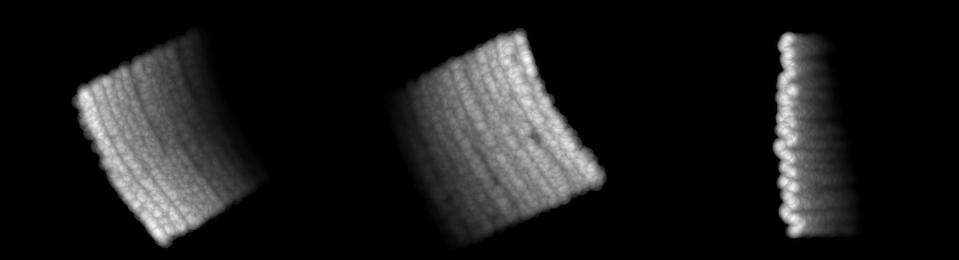




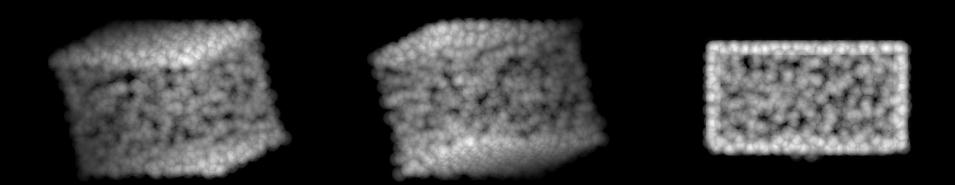
108_label_bench_pred_tv_stand.jpg

109_label_vase_pred_cup.jpg

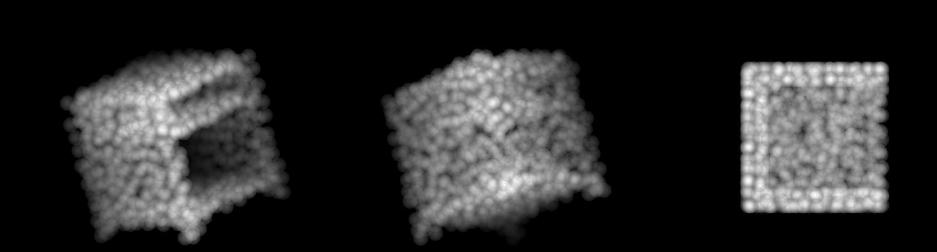




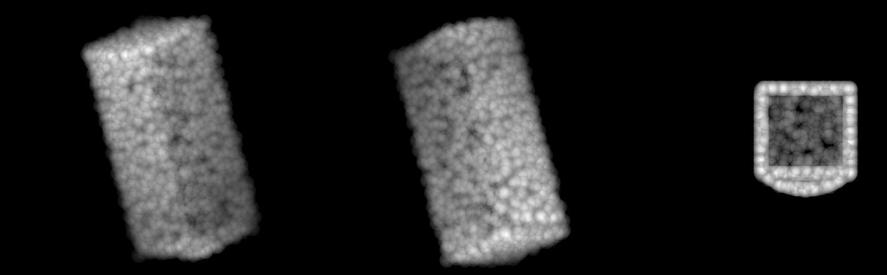
110_label_curtain_pred_laptop.jpg



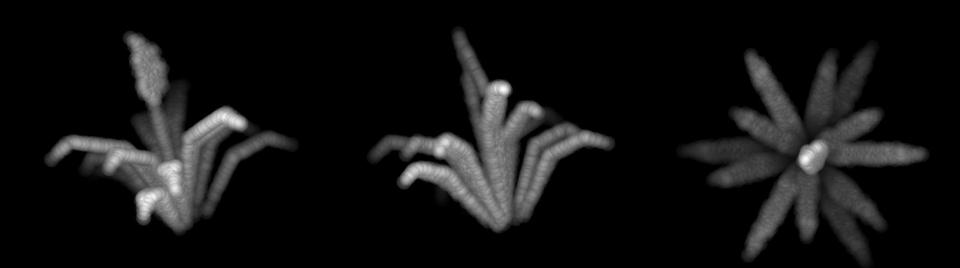
111_label_dresser_pred_glass_box.jpg



112_label_tv_stand_pred_night_stand.jpg

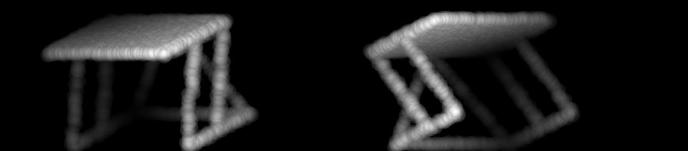


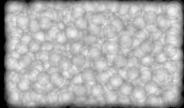
113_label_dresser_pred_wardrobe.jpg



114_label_plant_pred_sink.jpg

115_label_table_pred_desk.jpg

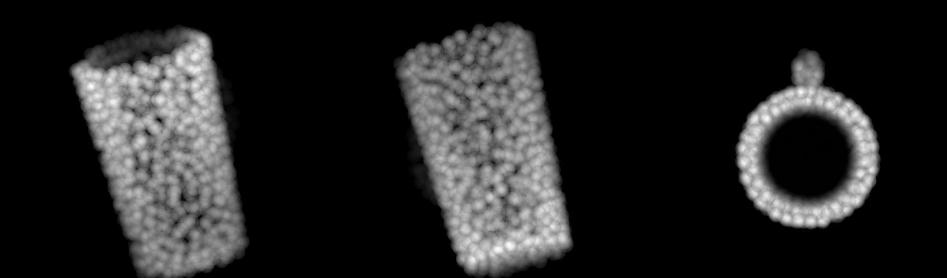






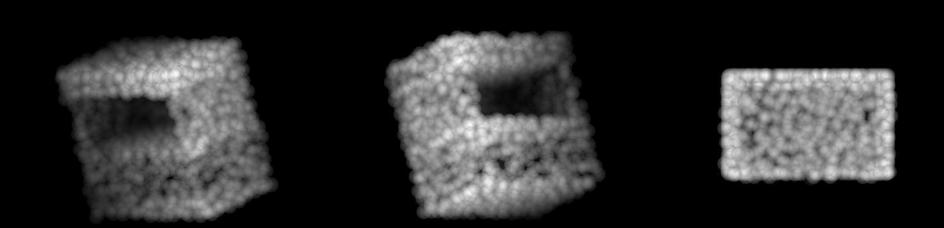
116_label_bed_pred_bench.jpg

117_label_cup_pred_vase.jpg

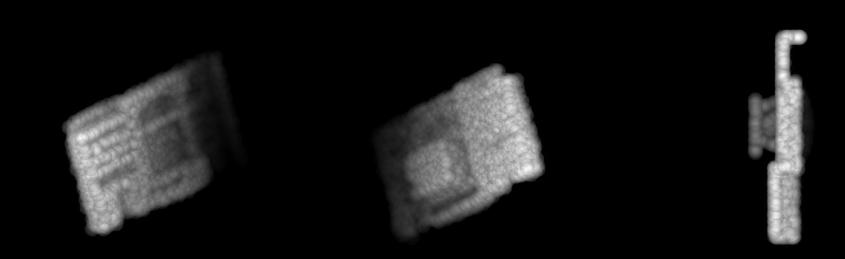




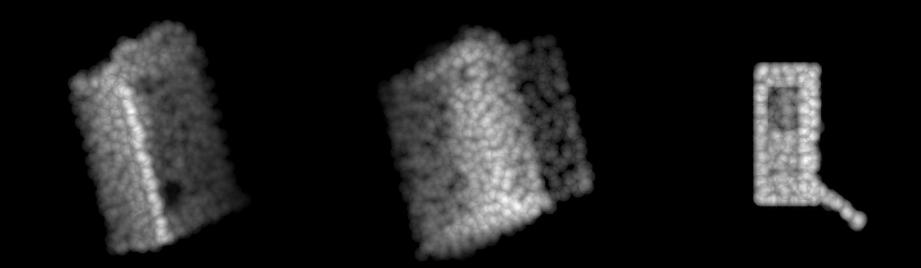
118_label_flower_pot_pred_plant.jpg



119_label_night_stand_pred_tv_stand.jpg

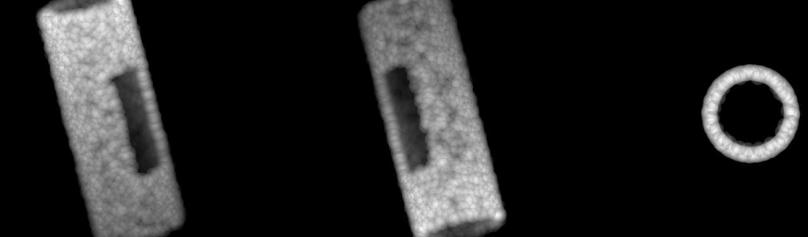


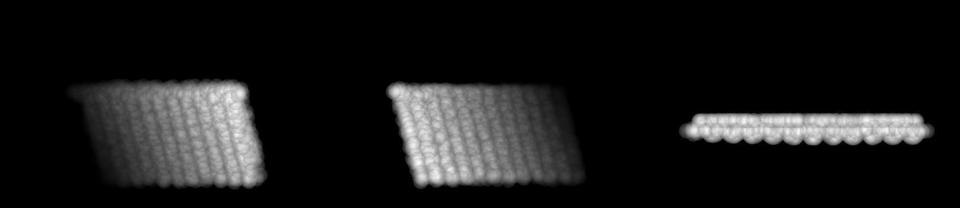
120_label_mantel_pred_monitor.jpg



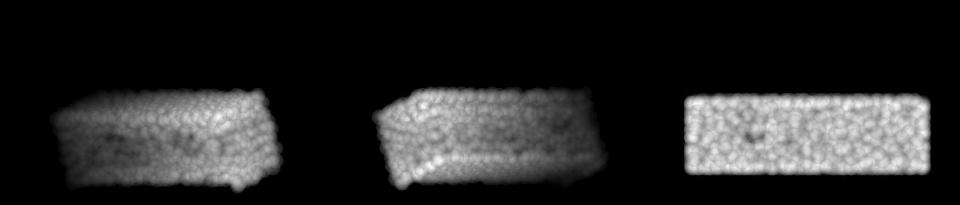
121_label_wardrobe_pred_xbox.jpg



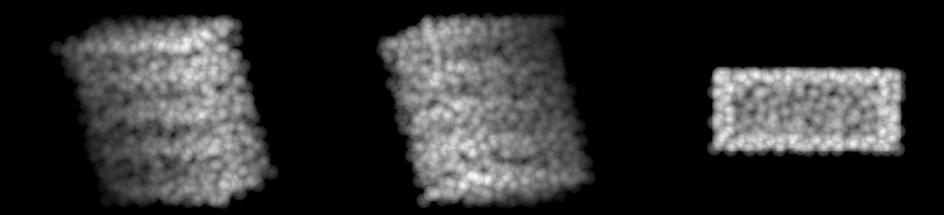




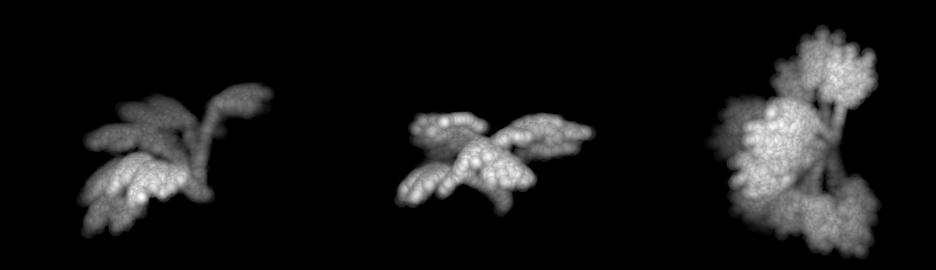
123_label_curtain_pred_monitor.jpg



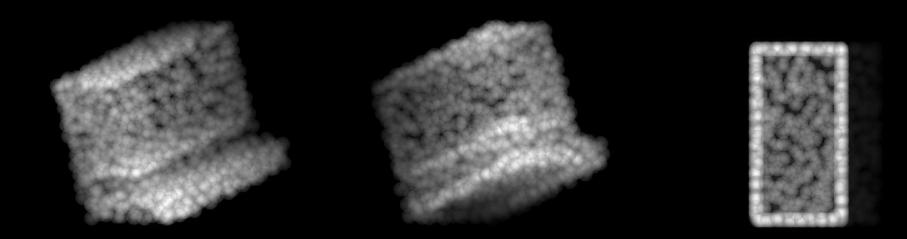
124_label_tv_stand_pred_bench.jpg



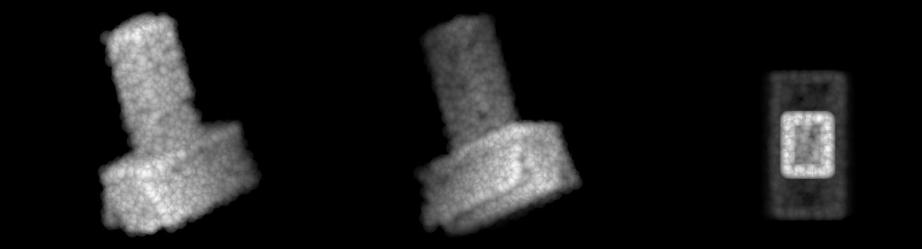
125_label_dresser_pred_bookshelf.jpg



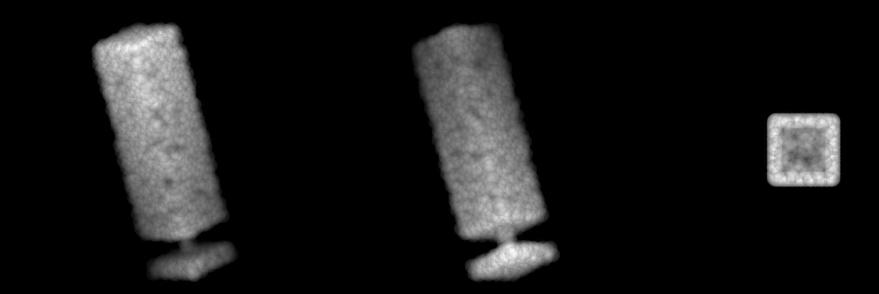
126_label_plant_pred_airplane.jpg



127_label_range_hood_pred_mantel.jpg

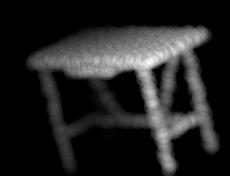


128_label_range_hood_pred_vase.jpg

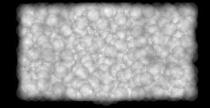


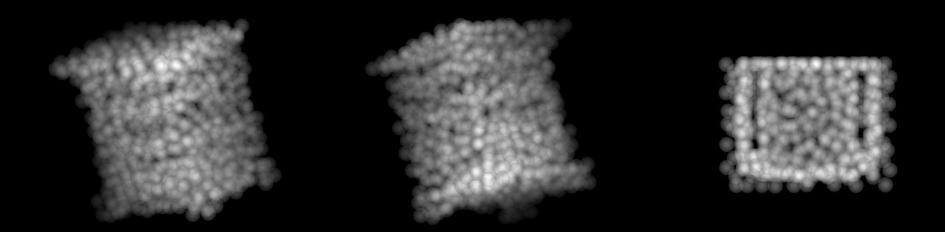
129_label_lamp_pred_dresser.jpg

130_label_desk_pred_table.jpg

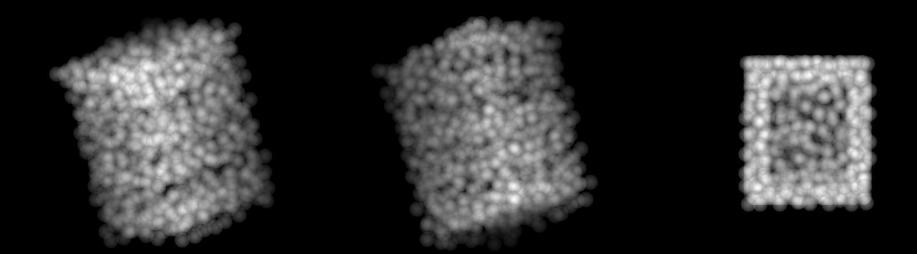




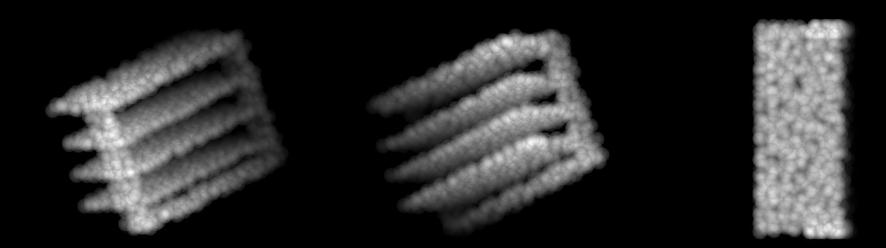




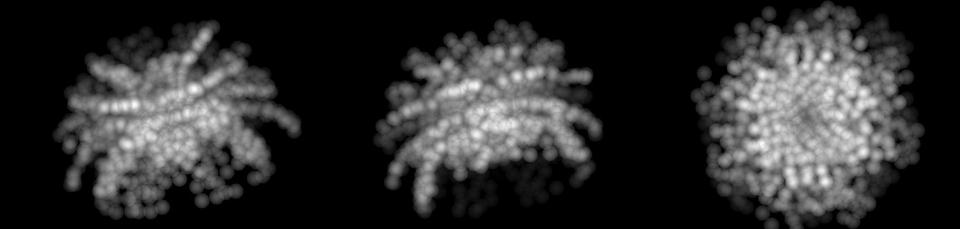
131_label_night_stand_pred_dresser.jpg



132_label_night_stand_pred_dresser.jpg



133_label_tv_stand_pred_bookshelf.jpg

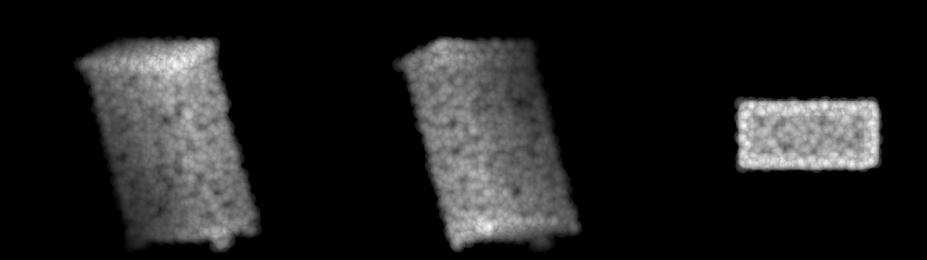


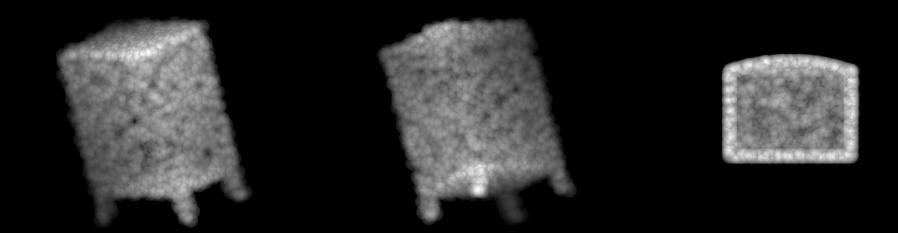
134_label_plant_pred_vase.jpg

135_label_tv_stand_pred_bench.jpg



136_label_dresser_pred_wardrobe.jpg



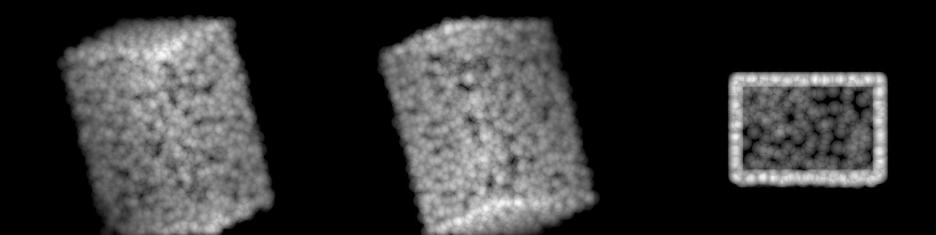


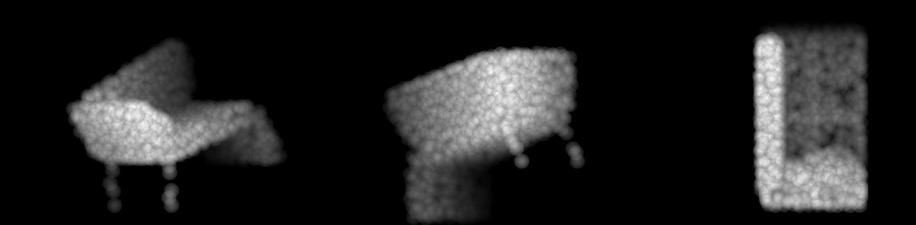
137_label_night_stand_pred_dresser.jpg

138_label_desk_pred_table.jpg

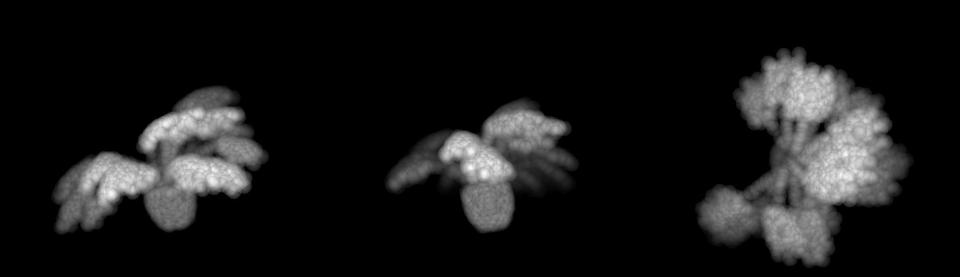




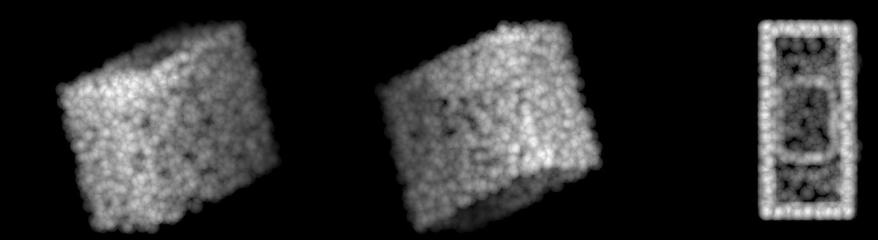




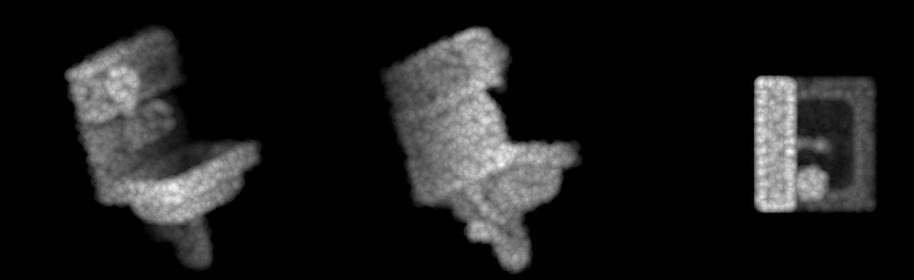
140_label_chair_pred_sofa.jpg



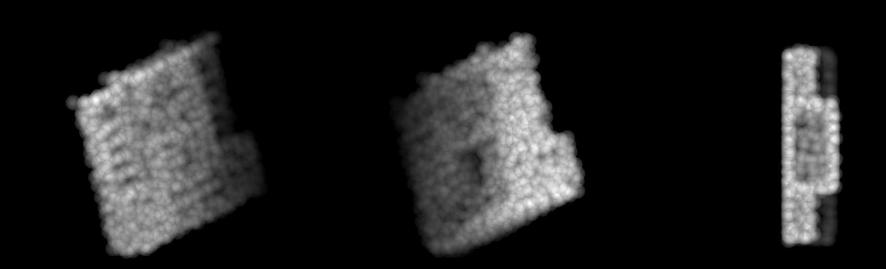
141_label_plant_pred_flower_pot.jpg



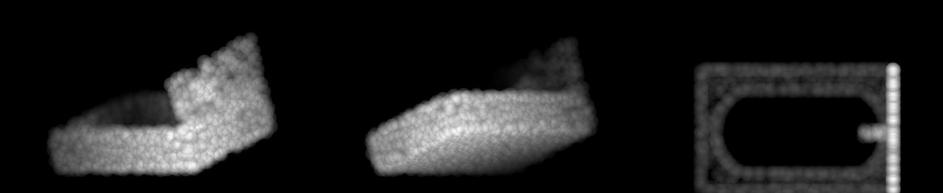
142_label_sink_pred_dresser.jpg



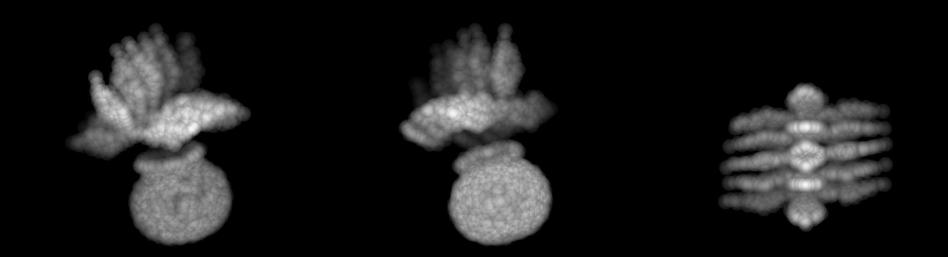
143_label_sink_pred_plant.jpg



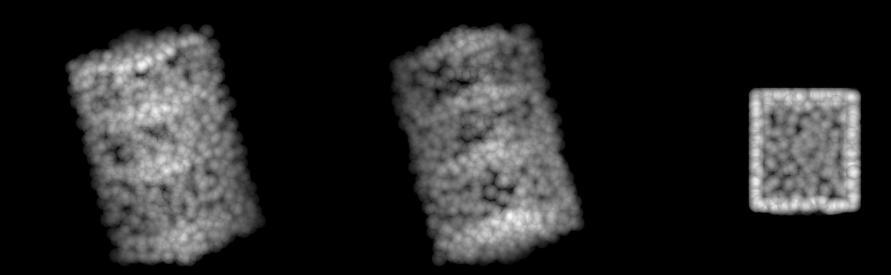
144_label_bookshelf_pred_wardrobe.jpg



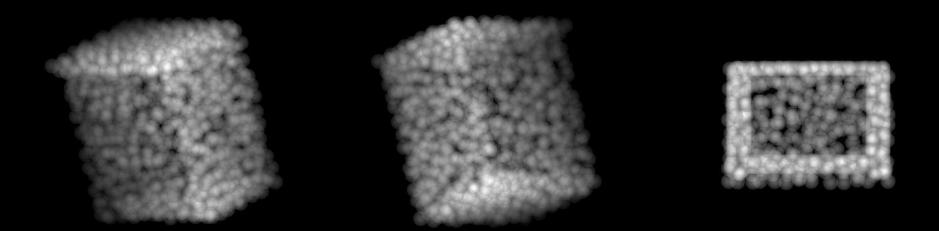
145_label_bathtub_pred_bed.jpg



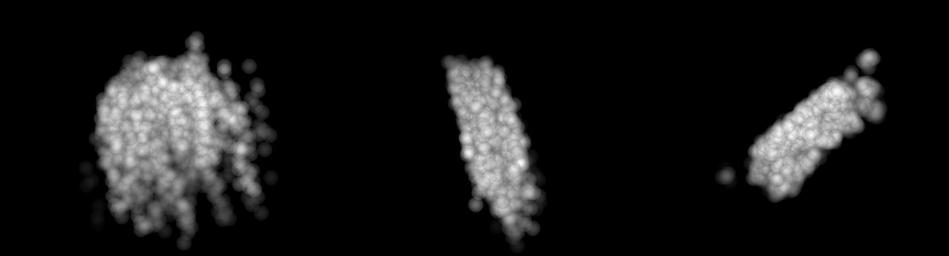
146_label_plant_pred_flower_pot.jpg



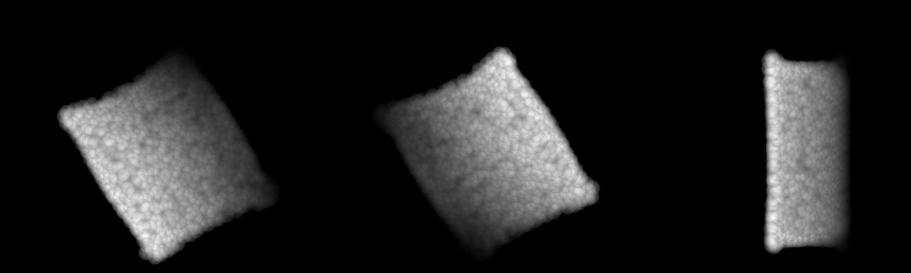
147_label_night_stand_pred_dresser.jpg



148 label_dresser_pred_night_stand.jpg

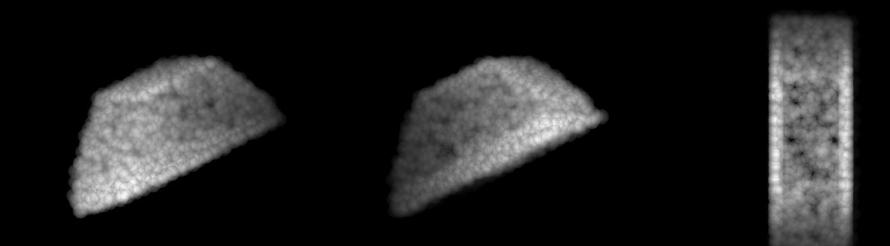


149_label_plant_pred_person.jpg

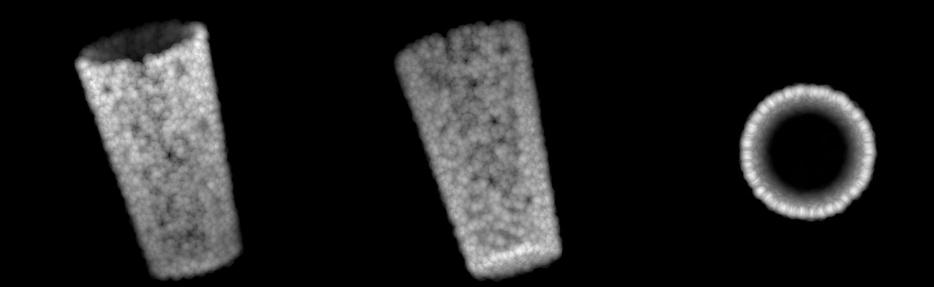


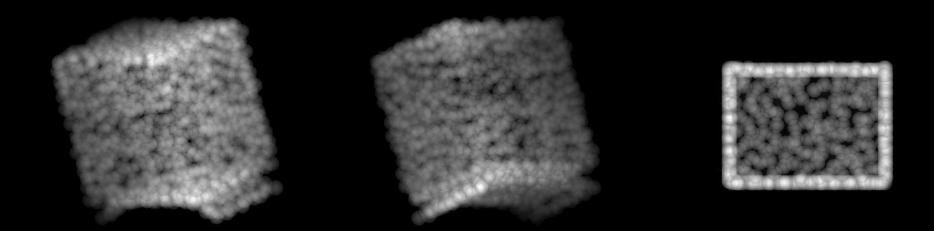
150_label_bench_pred_monitor.jpg

151_label_range_hood_pred_radio.jpg



152_label_vase_pred_cup.jpg

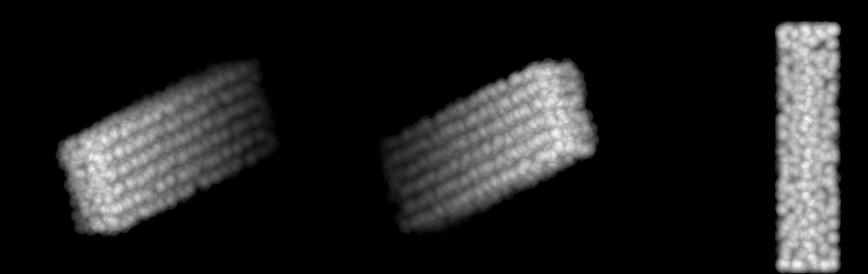




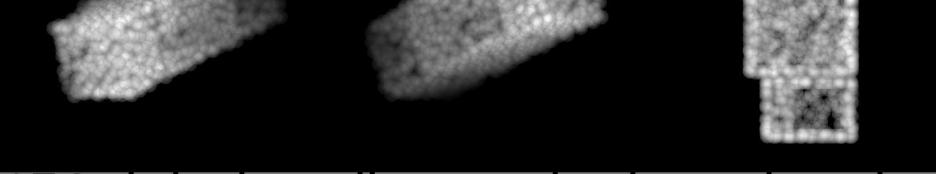
153 label_dresser_pred_night_stand.jpg



154_label_bottle_pred_vase.jpg



155_label_bookshelf_pred_tv_stand.jpg



156_label_radio_pred_glass_box.jpg

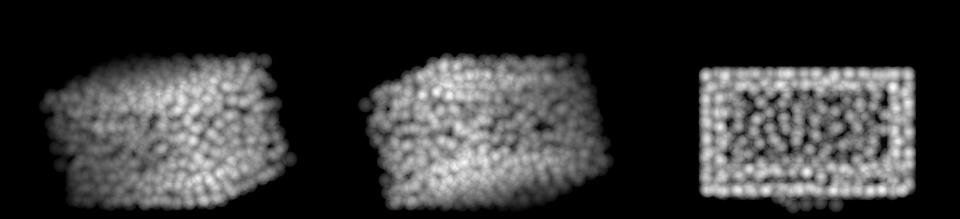


157_label_tv_stand_pred_bookshelf.jpg

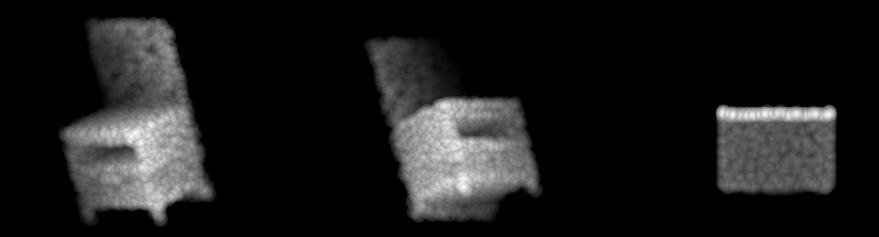


159_label_piano_pred_table.jpg

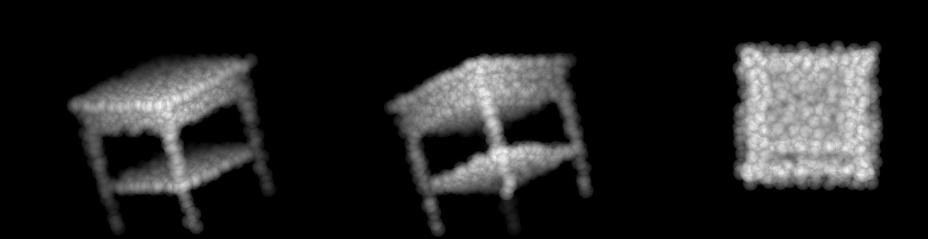




160_label_night_stand_pred_glass_box.jpg

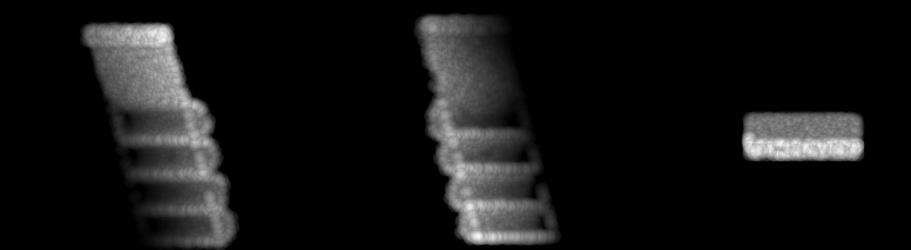


161 label_night_stand_pred_dresser.jpg

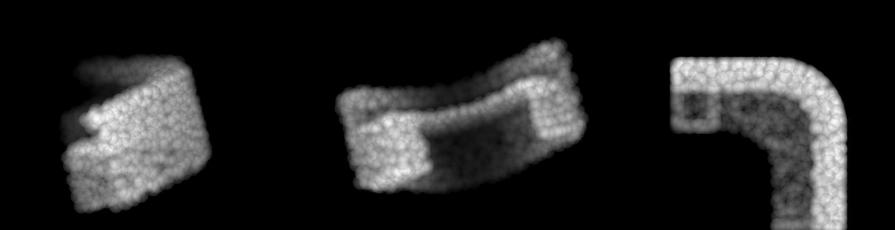


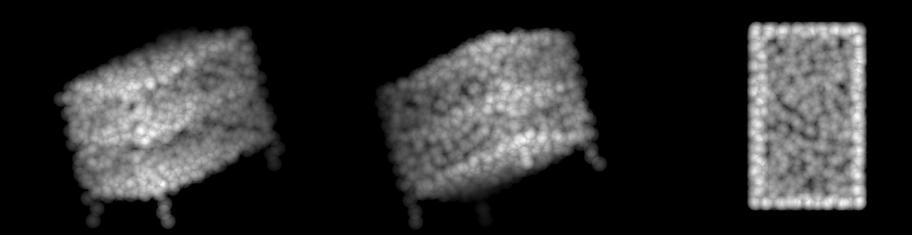
162_label_night_stand_pred_table.jpg





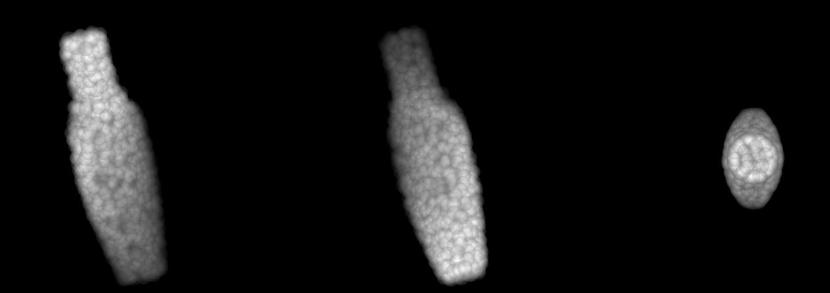
164_label_desk_pred_sofa.jpg



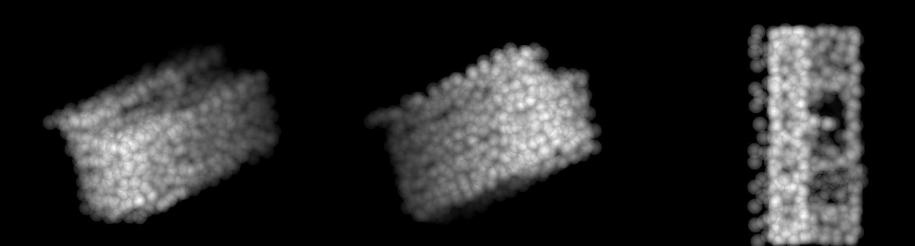


165_label_tv_stand_pred_night_stand.jpg

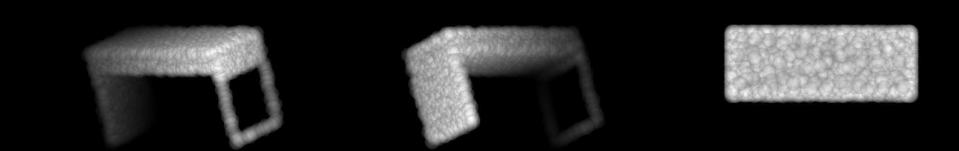
166_label_bottle_pred_vase.jpg

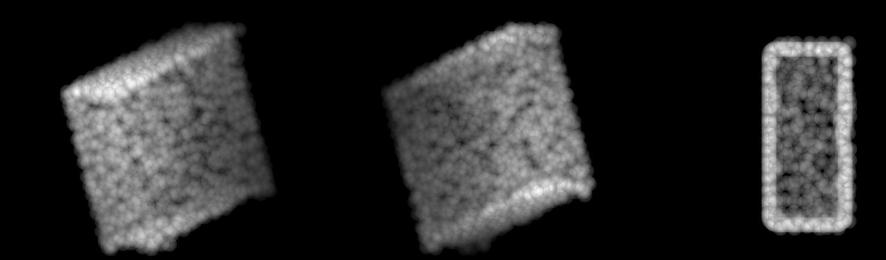


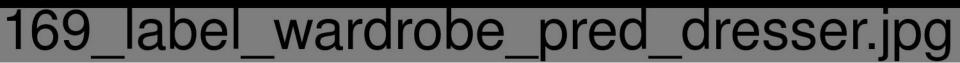
167_label_sink_pred_sofa.jpg



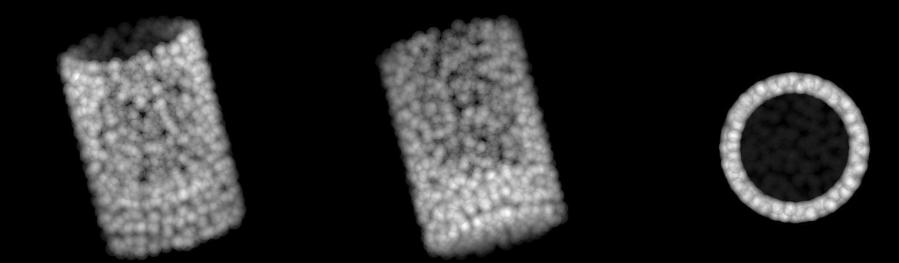
168_label_table_pred_desk.jpg

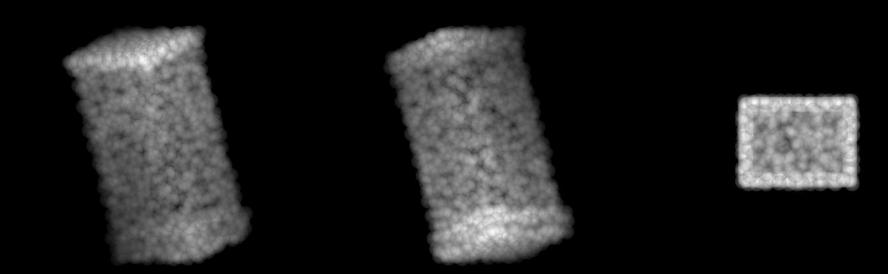






170_label_vase_pred_cup.jpg

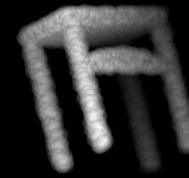


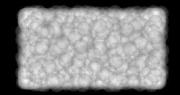


171_label_night_stand_pred_dresser.jpg

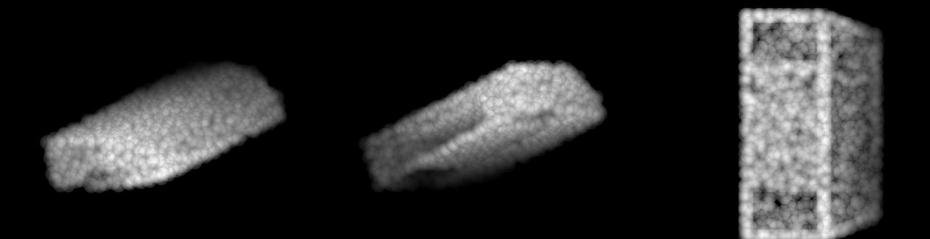
172_label_night_stand_pred_desk.jpg



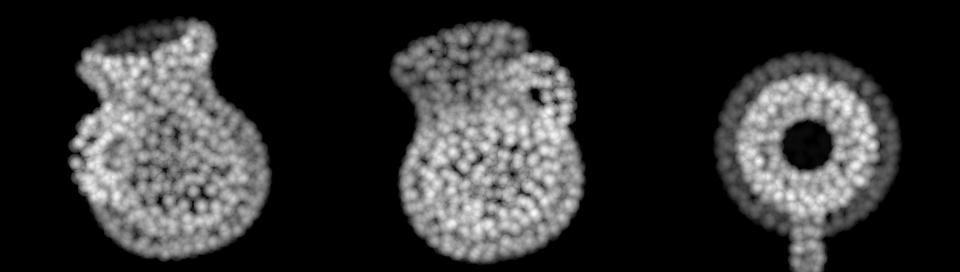


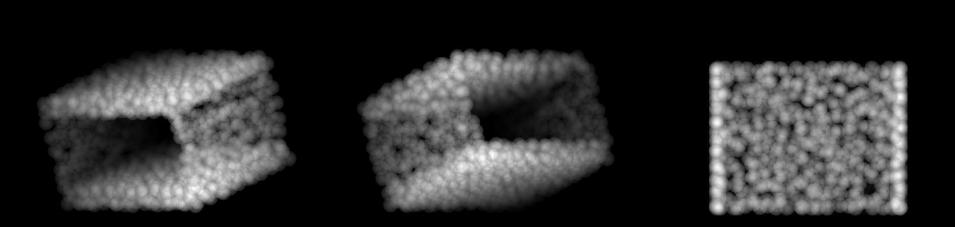


173_label_range_hood_pred_bed.jpg

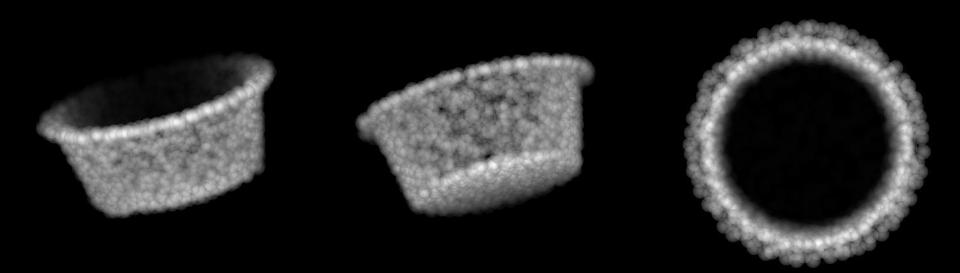


174_label_cup_pred_vase.jpg





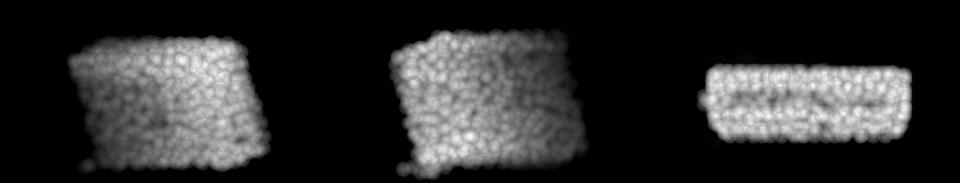
175_label_night_stand_pred_radio.jpg



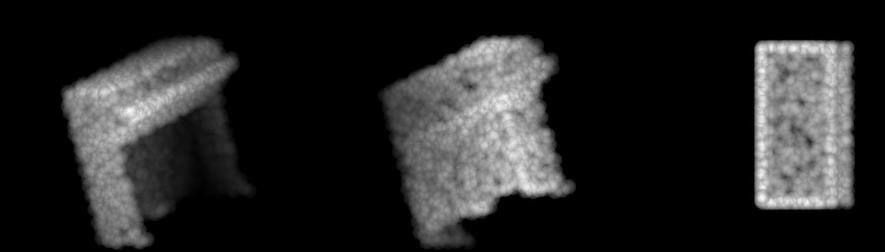
176_label_cup_pred_bowl.jpg

177_label_plant_pred_cup.jpg

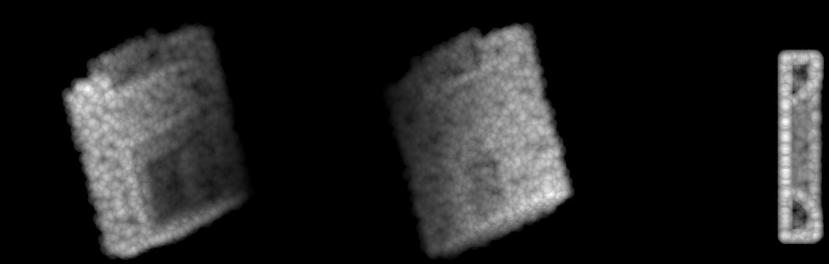




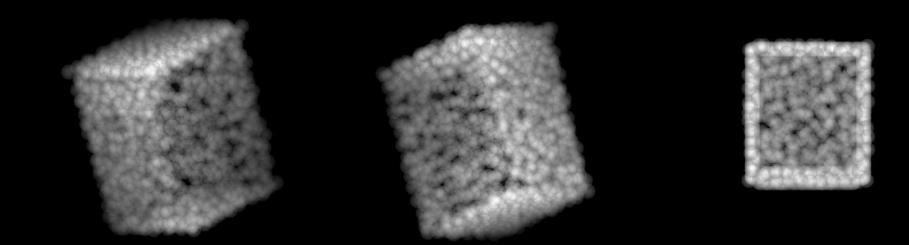
178_label_radio_pred_desk.jpg



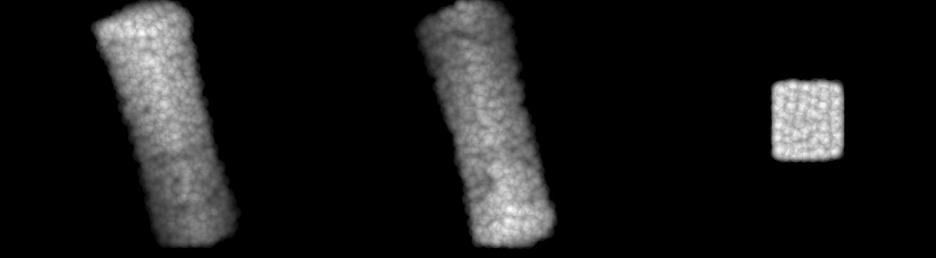
179_label_piano_pred_mantel.jpg



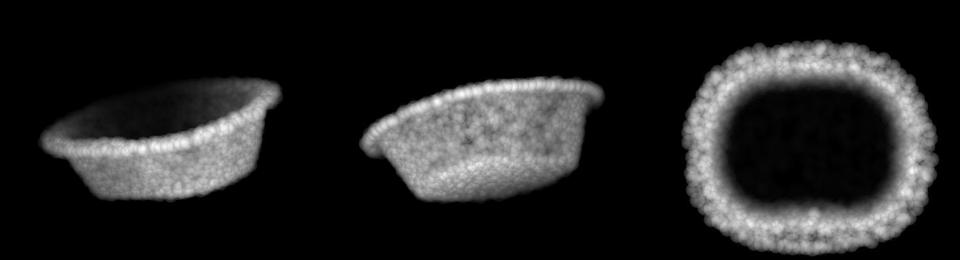
180_label_mantel_pred_bookshelf.jpg



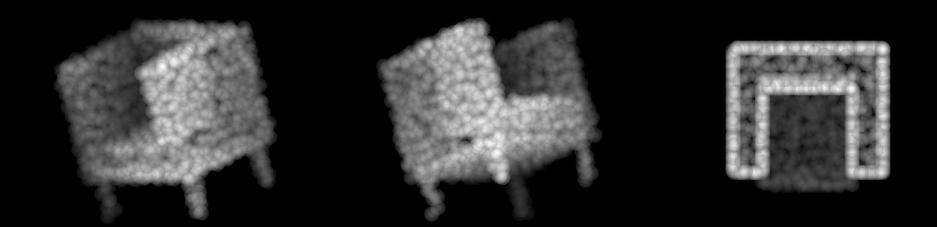
181 label_dresser_pred_night_stand.jpg



182_label_xbox_pred_bookshelf.jpg

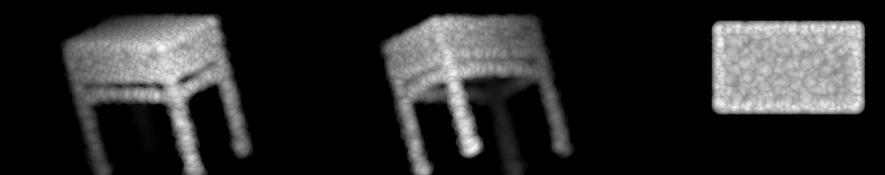


183_label_bathtub_pred_bowl.jpg

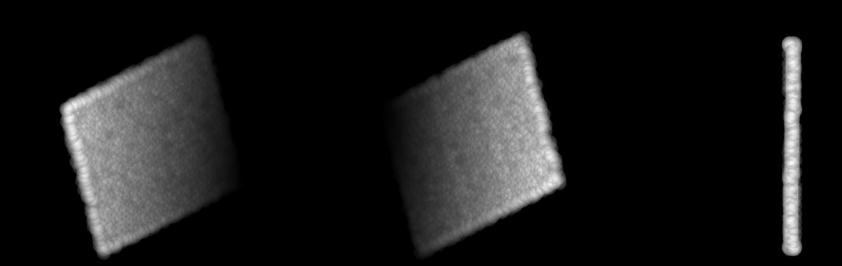


184_label_sofa_pred_chair.jpg

185_label_night_stand_pred_table.jpg



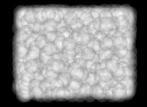


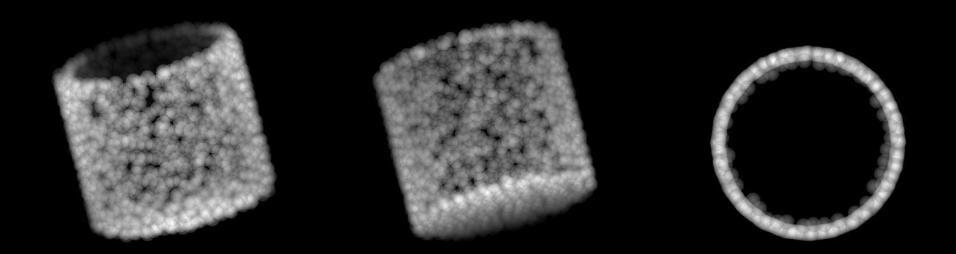




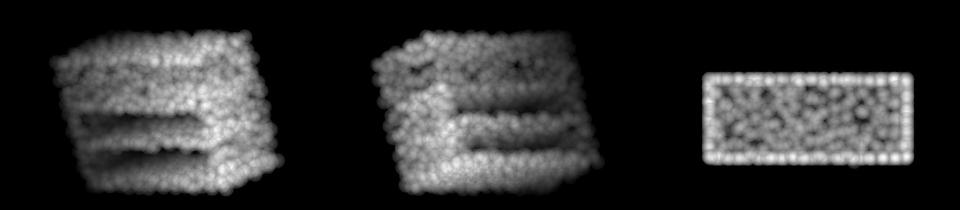




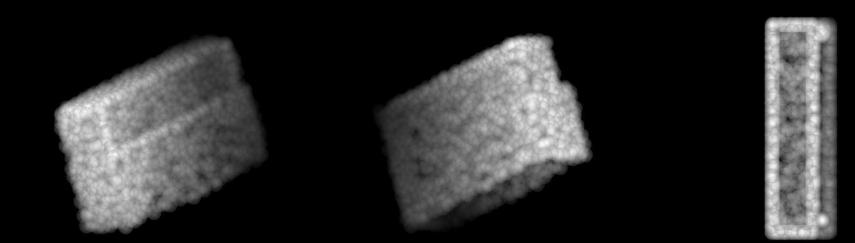




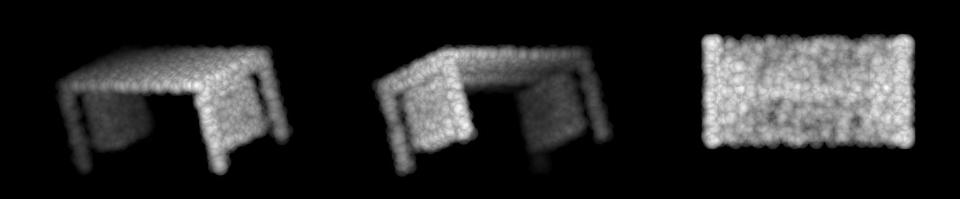
188_label_vase_pred_flower_pot.jpg



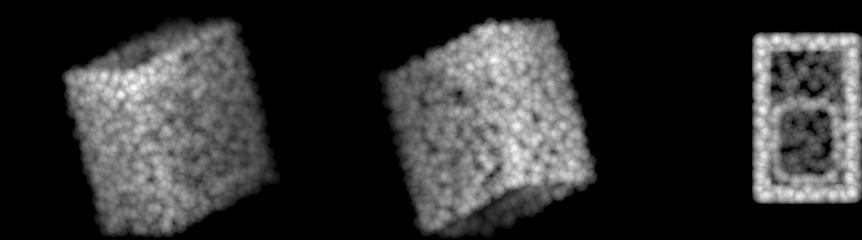
189_label_night_stand_pred_tv_stand.jpg



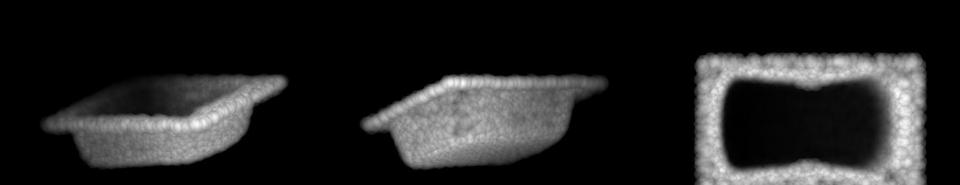
190_label_piano_pred_mantel.jpg



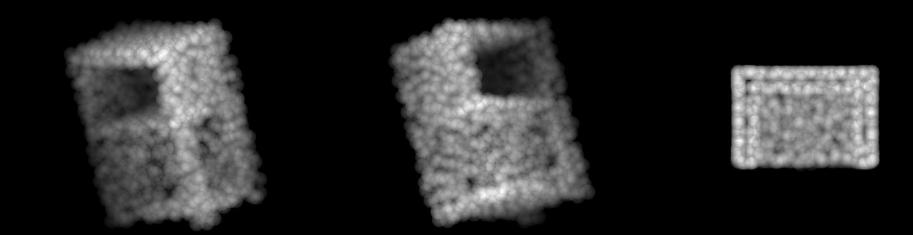
191_label_desk_pred_tv_stand.jpg



192_label_sink_pred_dresser.jpg

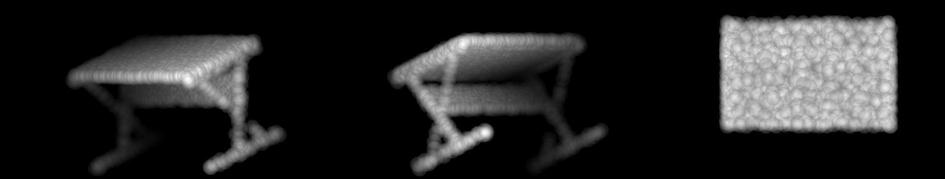


193_label_bathtub_pred_sink.jpg



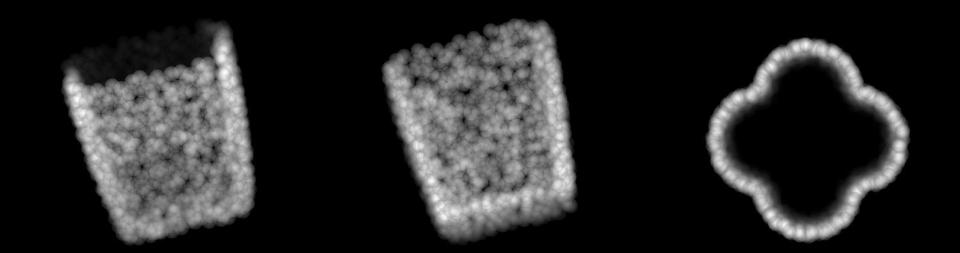
194_label_night_stand_pred_tv_stand.jpg

195_label_table_pred_desk.jpg



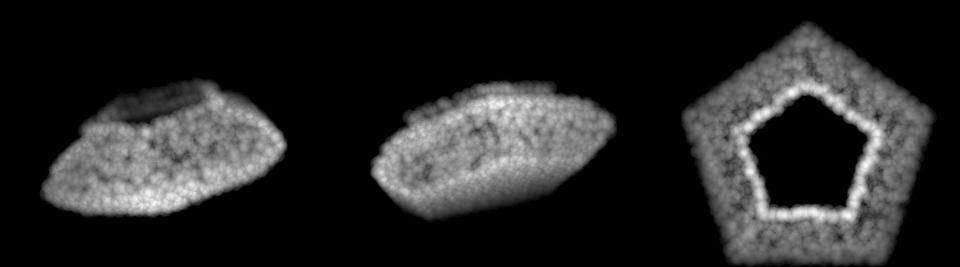


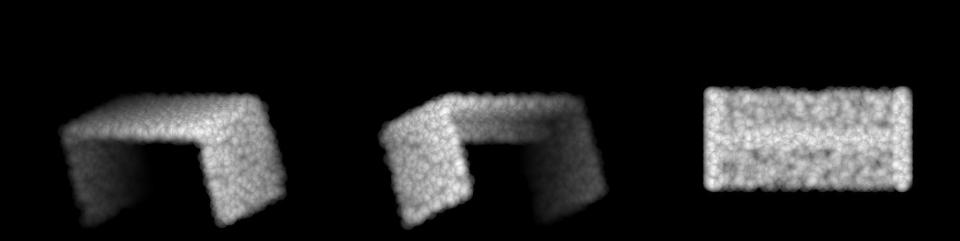
196_label_piano_pred_bench.jpg



197_label_vase_pred_flower_pot.jpg

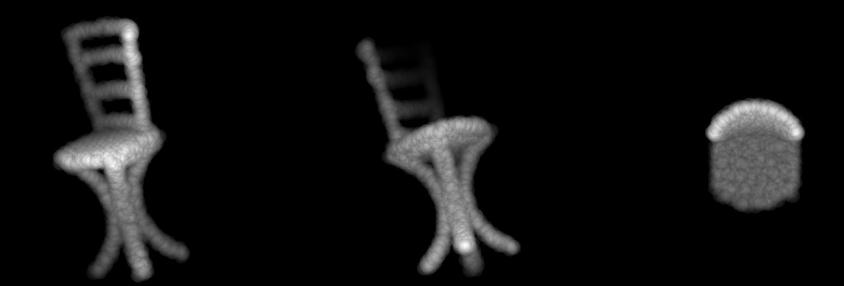
198_label_vase_pred_tent.jpg

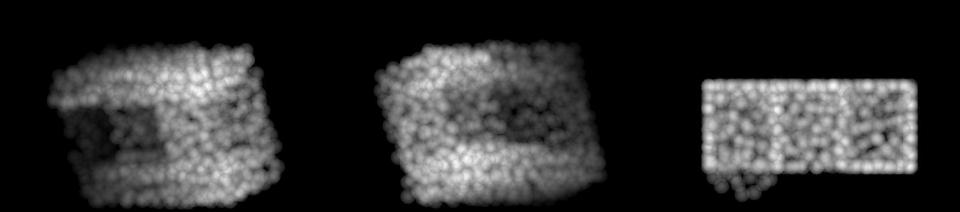




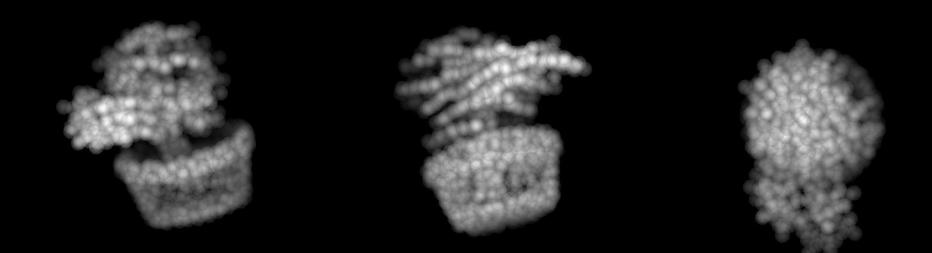
199_label_table_pred_desk.jpg

200_label_stool_pred_chair.jpg



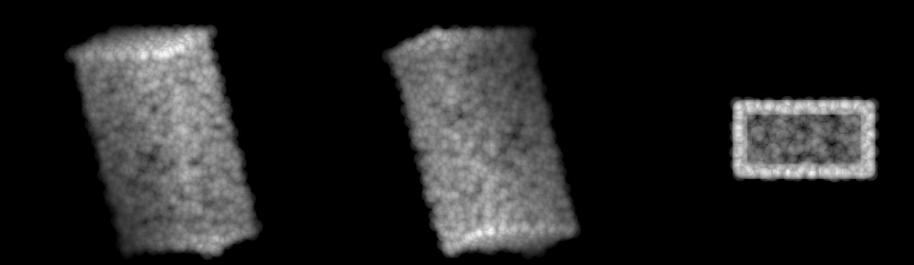


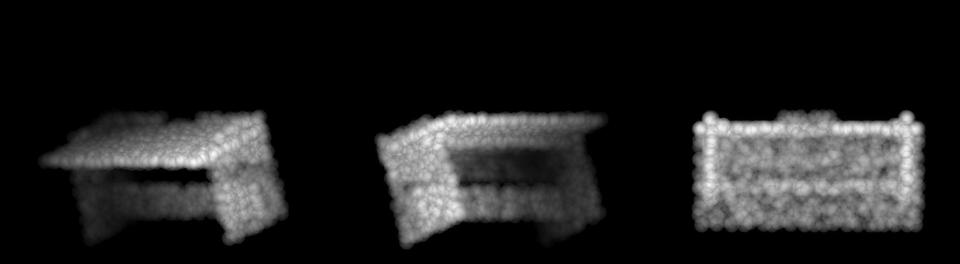
201_label_desk_pred_tv_stand.jpg



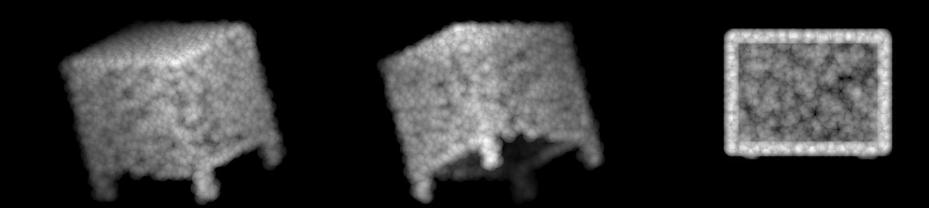
202_label_flower_pot_pred_plant.jpg





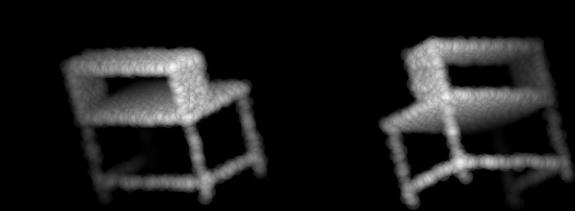


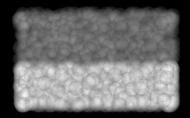
204_label_desk_pred_bench.jpg

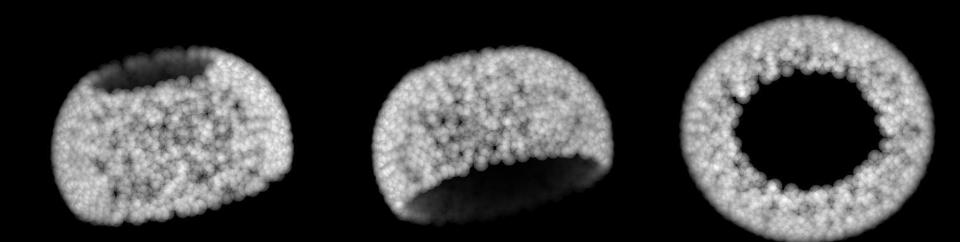


205_label_dresser_pred_night_stand.jpg

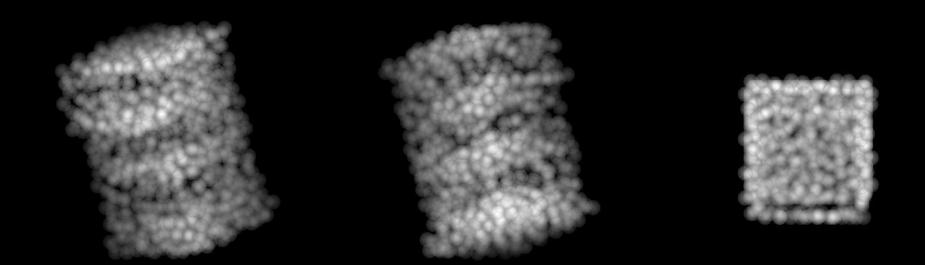








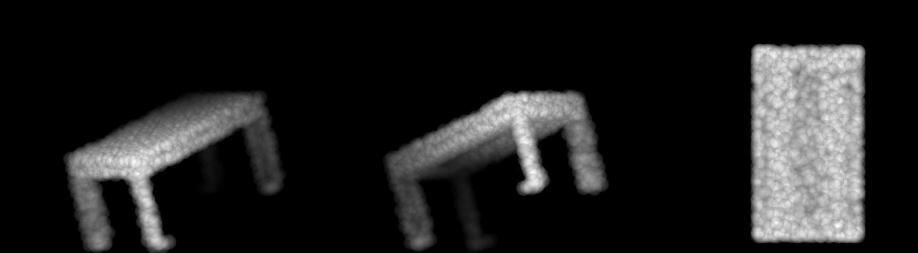
207_label_vase_pred_bowl.jpg



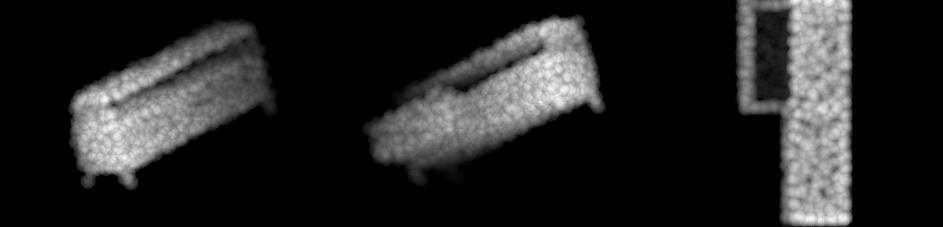
208_label_night_stand_pred_dresser.jpg

209_label_bottle_pred_stool.jpg

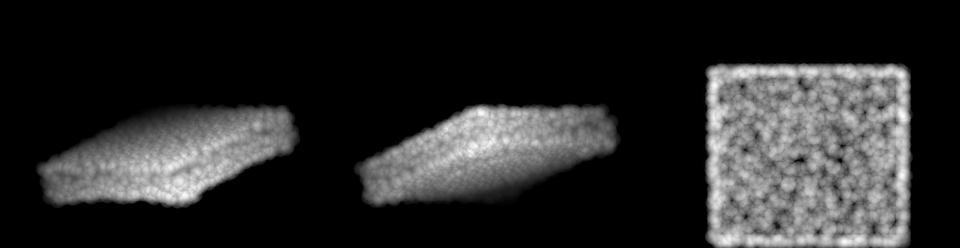




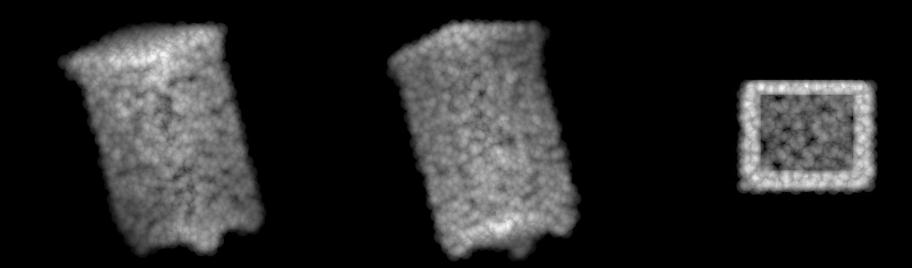
210_label_bench_pred_table.jpg



211_label_tv_stand_pred_desk.jpg



212_label_radio_pred_piano.jpg



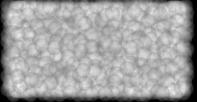
213_label_night_stand_pred_dresser.jpg

214_label_plant_pred_radio.jpg

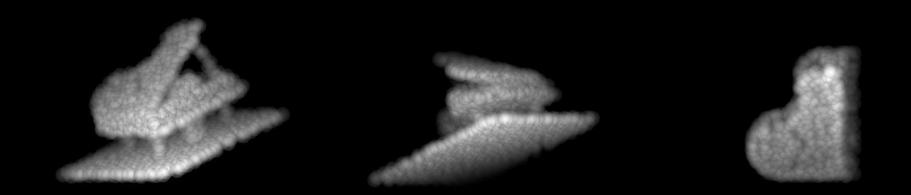






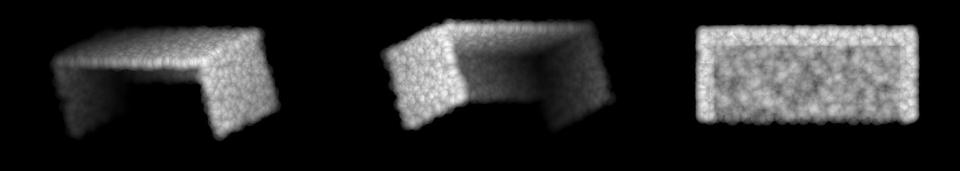




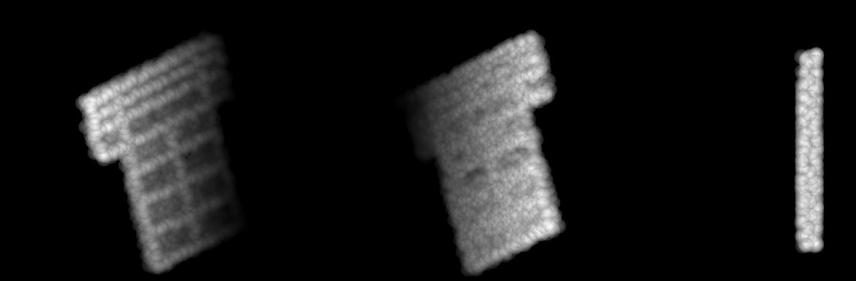




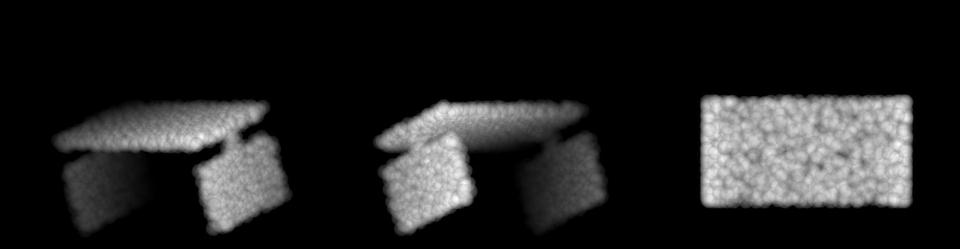
217_label_bench_pred_table.jpg



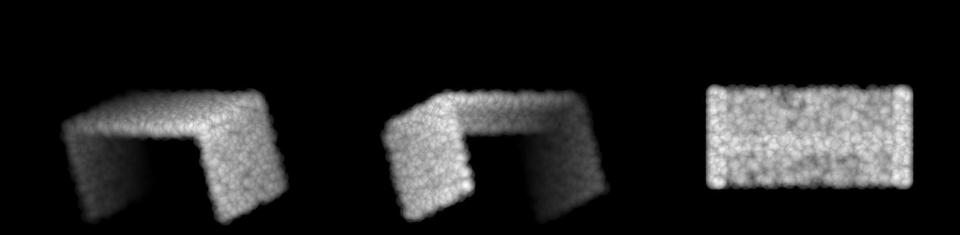
218_label_table_pred_desk.jpg



219_label_bookshelf_pred_curtain.jpg

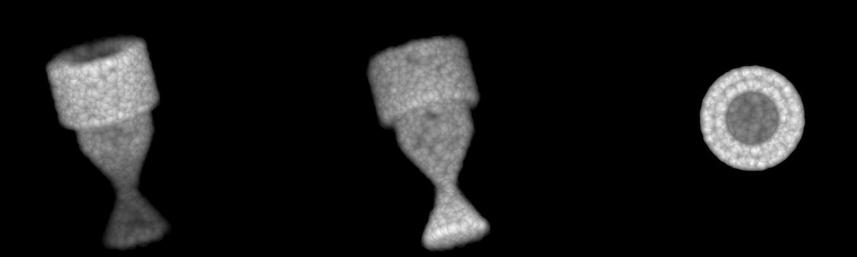


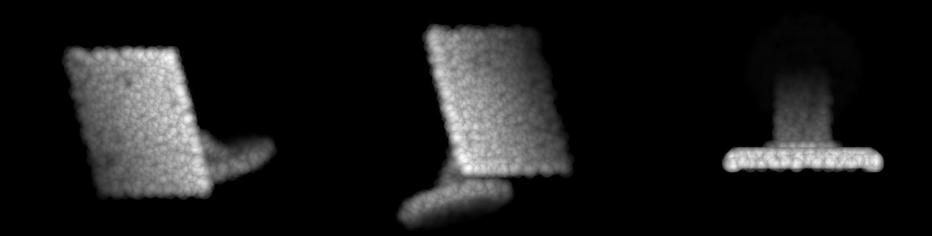
220_label_table_pred_tv_stand.jpg



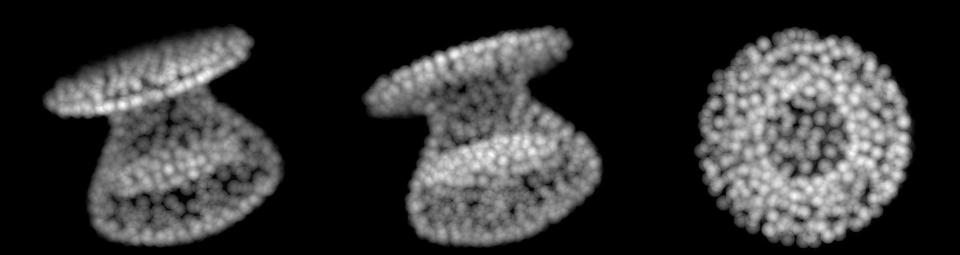
221_label_table_pred_desk.jpg

222_label_cup_pred_vase.jpg

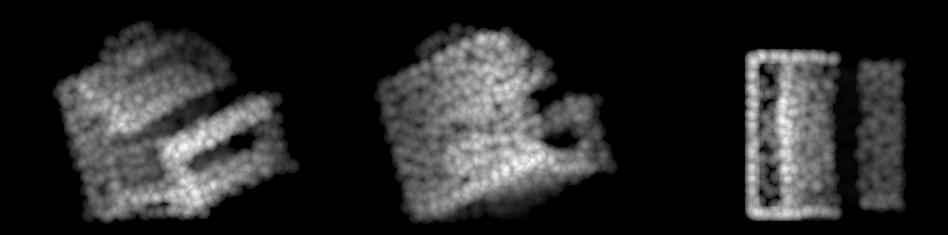




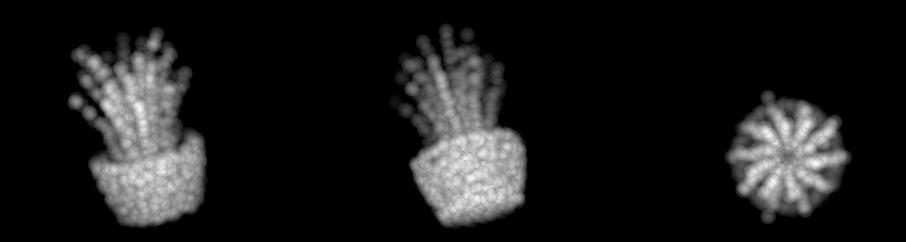
223_label_monitor_pred_laptop.jpg



224_label_vase_pred_night_stand.jpg



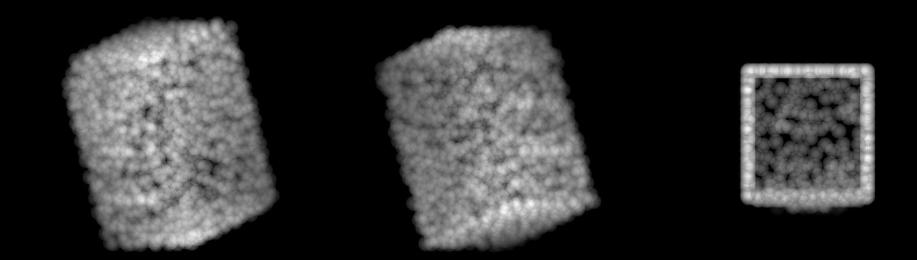
225_label_piano_pred_stairs.jpg



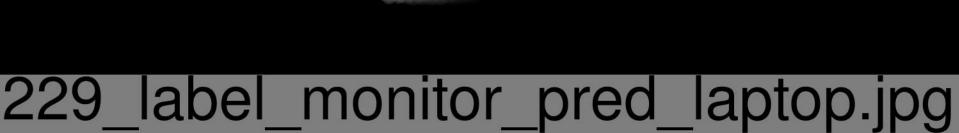
226_label_flower_pot_pred_plant.jpg

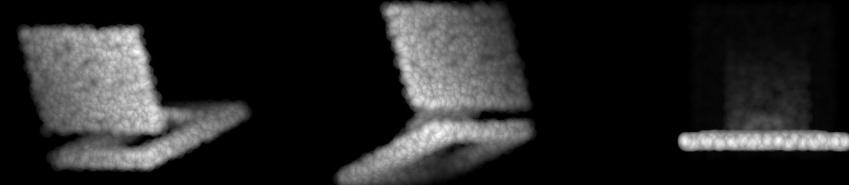


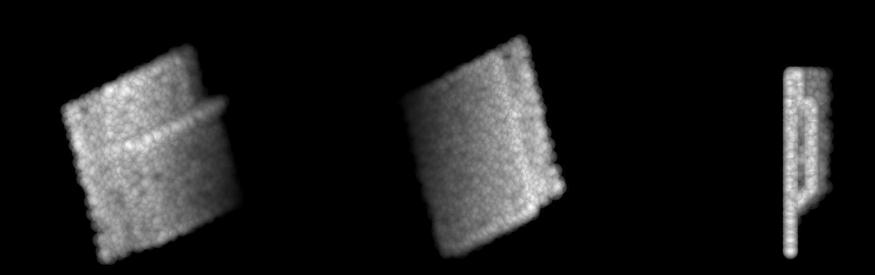
227_label_plant_pred_flower_pot.jpg



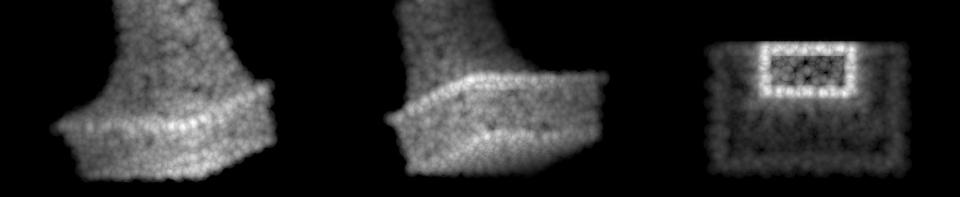
228_label_night_stand_pred_dresser.jpg



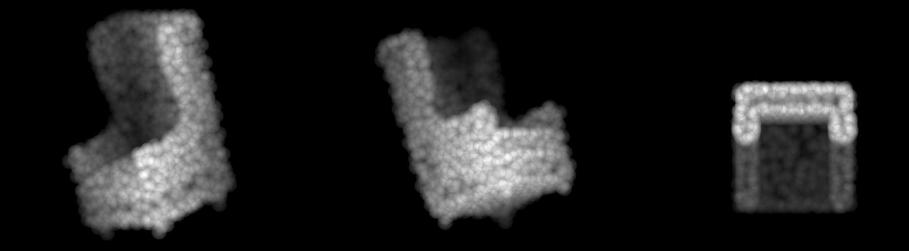




230_label_mantel_pred_monitor.jpg

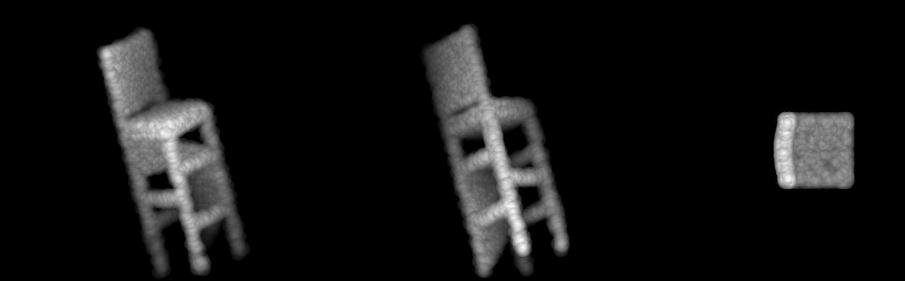


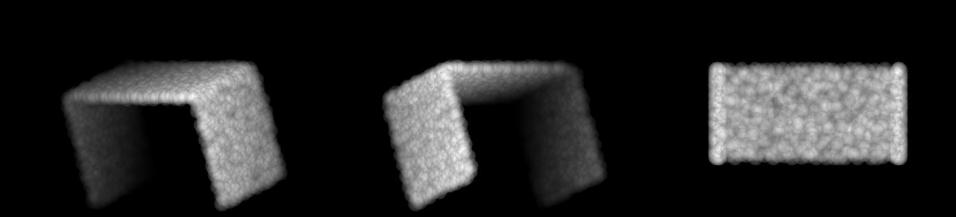
231_label_range_hood_pred_piano.jpg



232_label_sofa_pred_chair.jpg

233_label_stool_pred_bookshelf.jpg

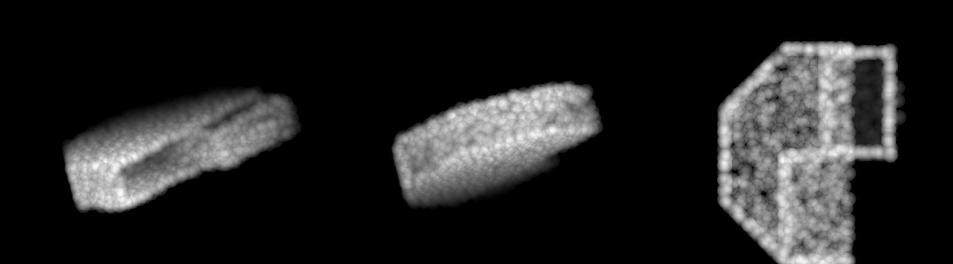




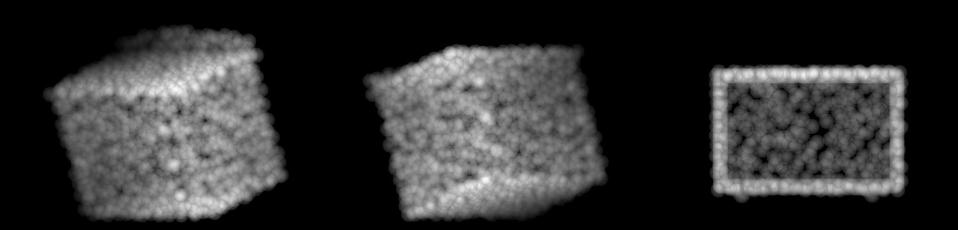
234_label_table_pred_tv_stand.jpg

235_label_desk_pred_night_stand.jpg

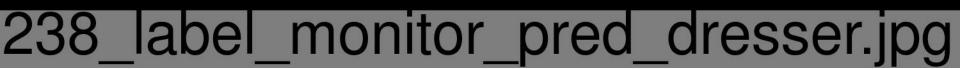


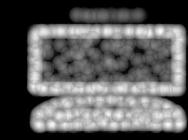


236_label_tv_stand_pred_radio.jpg

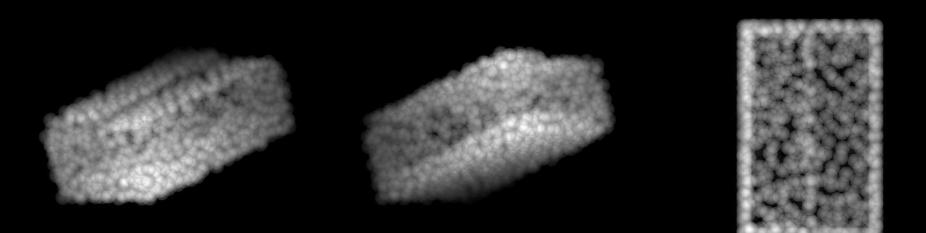


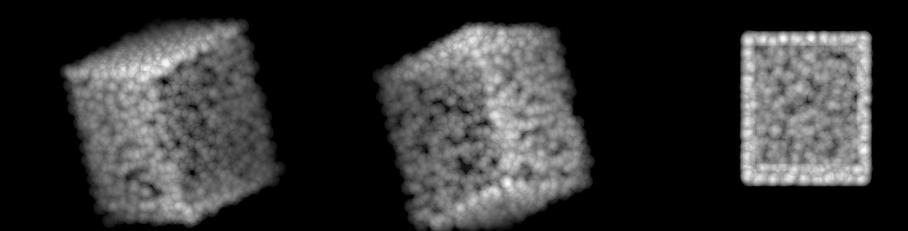
237_label_dresser_pred_sink.jpg





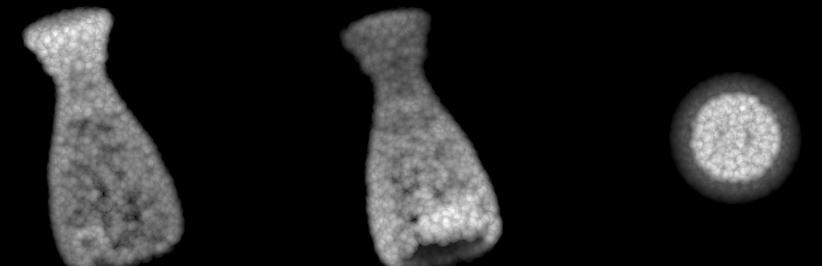




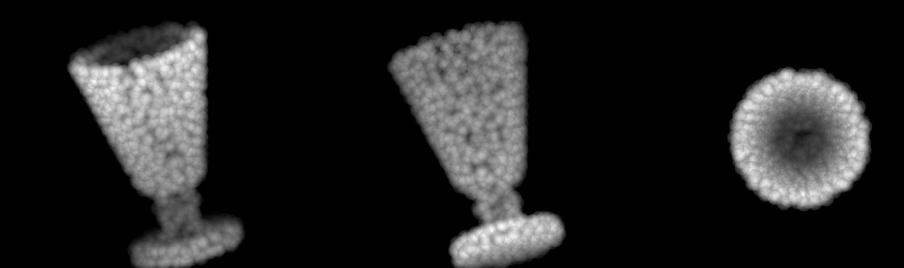


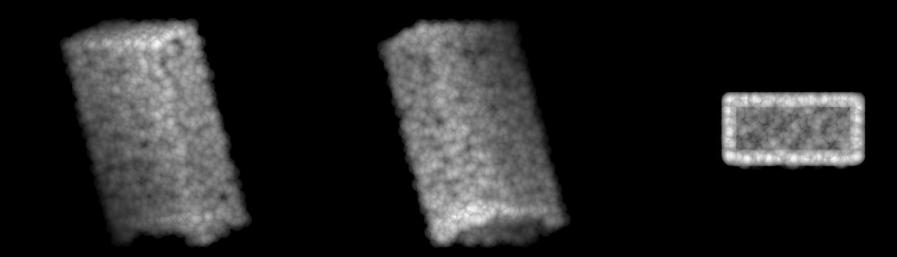
240_label_night_stand_pred_dresser.jpg



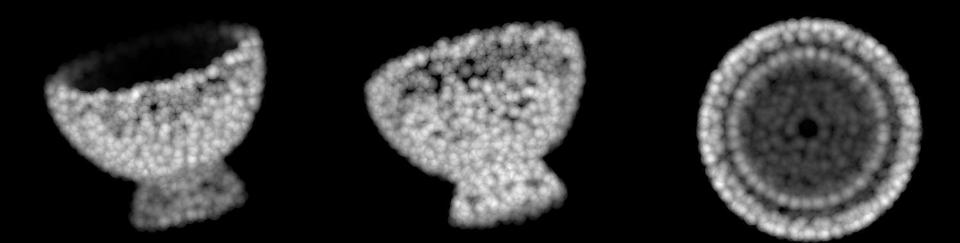


242_label_cup_pred_vase.jpg

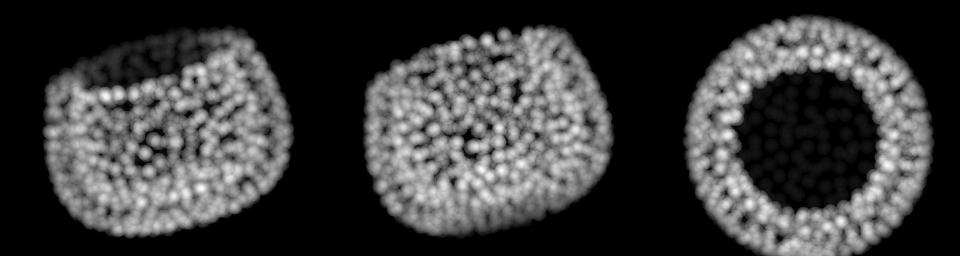




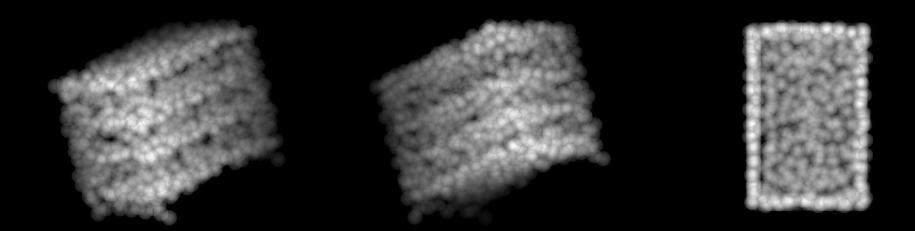
243_label_dresser_pred_wardrobe.jpg



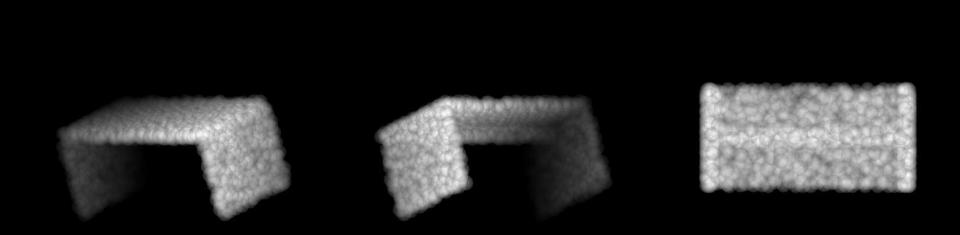
244_label_vase_pred_bowl.jpg



245_label_bowl_pred_vase.jpg

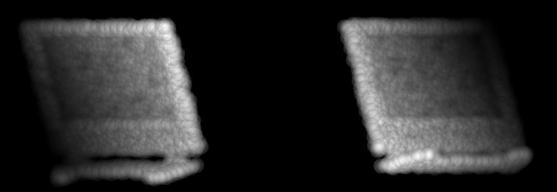


246_label_tv_stand_pred_dresser.jpg

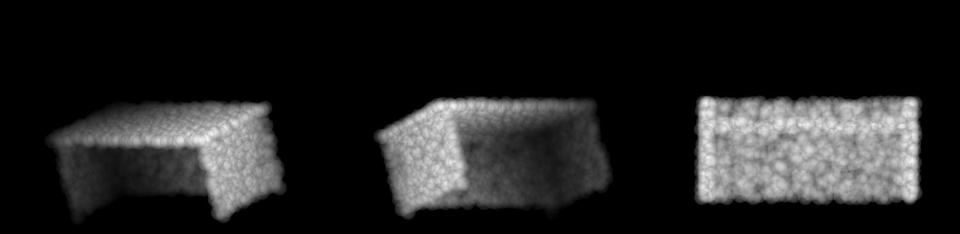


247_label_table_pred_tv_stand.jpg

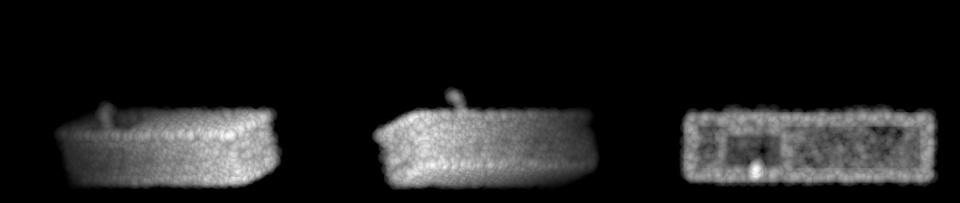
248_label_monitor_pred_mantel.jpg



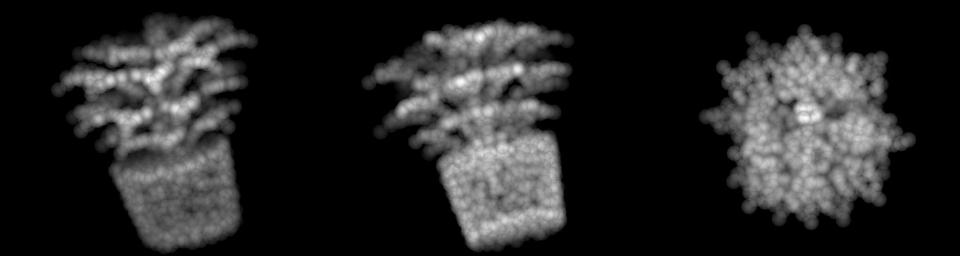
Convertient and watter



249_label_table_pred_desk.jpg



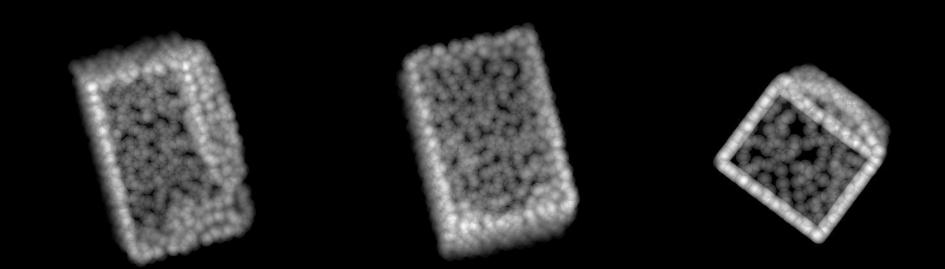
250_label_sink_pred_tv_stand.jpg



251_label_flower_pot_pred_plant.jpg



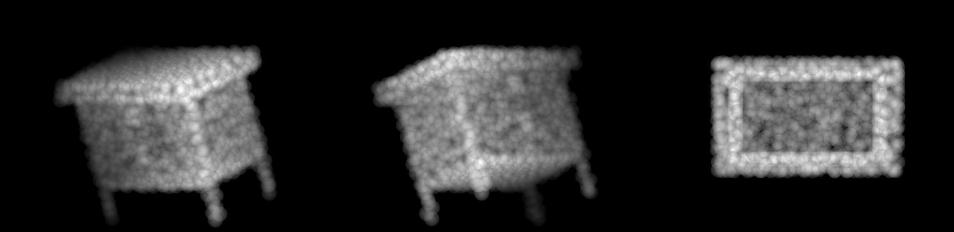
252_label_desk_pred_sofa.jpg



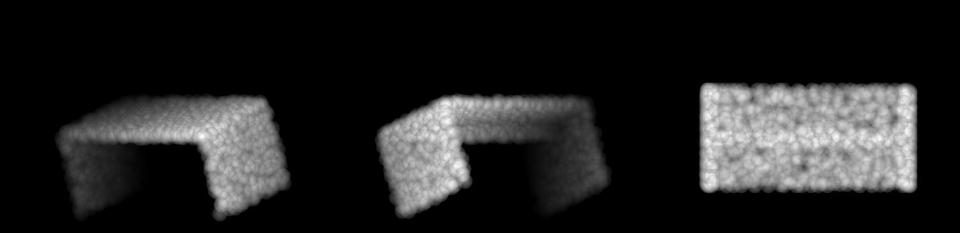
253_label_radio_pred_wardrobe.jpg







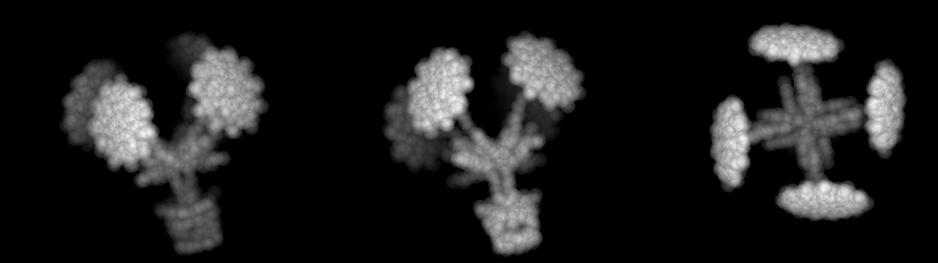
255_label_dresser_pred_night_stand.jpg



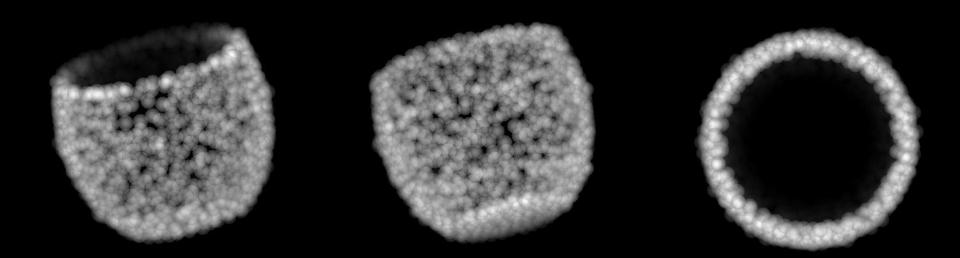
256_label_table_pred_tv_stand.jpg







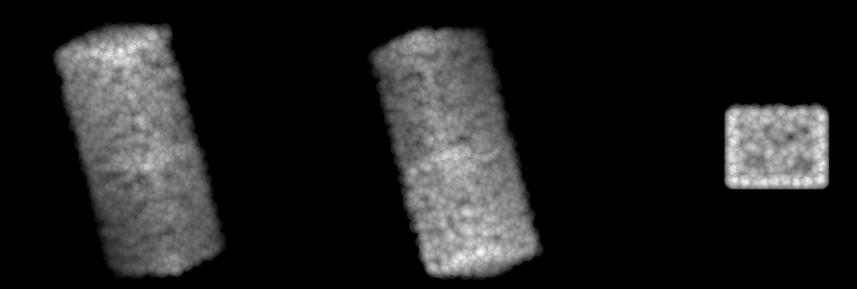
258_label_flower_pot_pred_plant.jpg



259_label_flower_pot_pred_vase.jpg

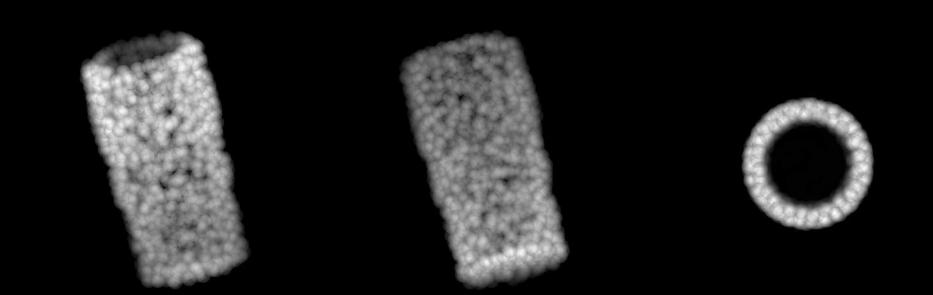
260_label_bottle_pred_vase.jpg

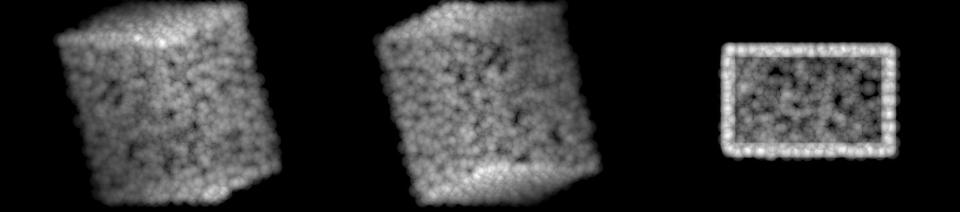




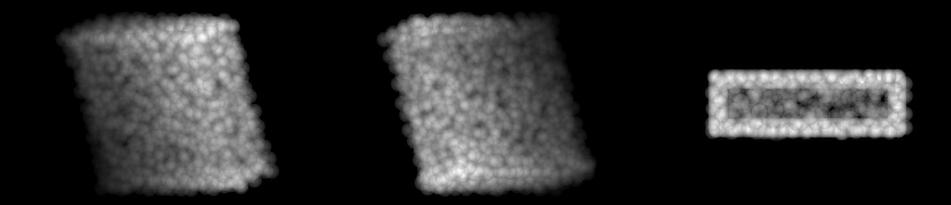
261_label_wardrobe_pred_bookshelf.jpg

262_label_cup_pred_vase.jpg





263_label_night_stand_pred_dresser.jpg

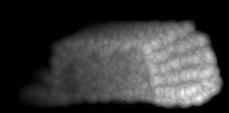


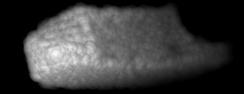
264_label_dresser_pred_wardrobe.jpg

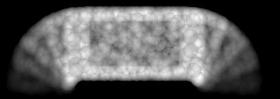


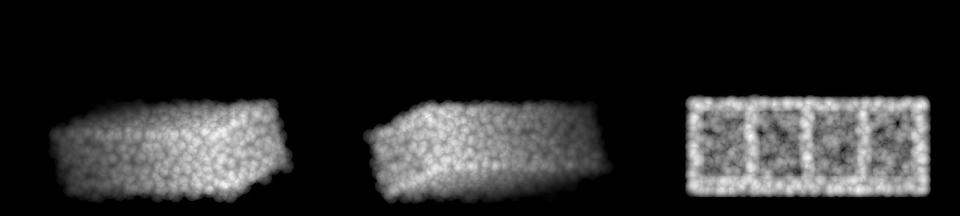




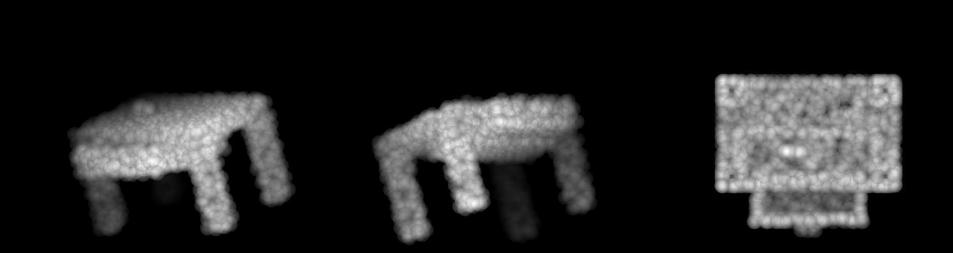




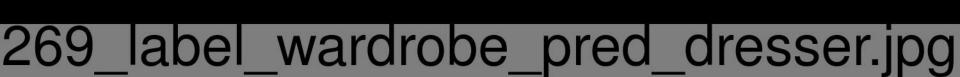


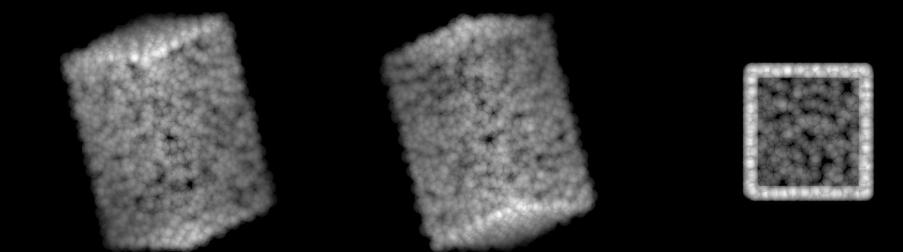


267_label_tv_stand_pred_glass_box.jpg



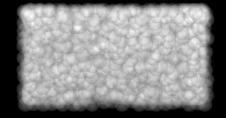
268_label_desk_pred_piano.jpg

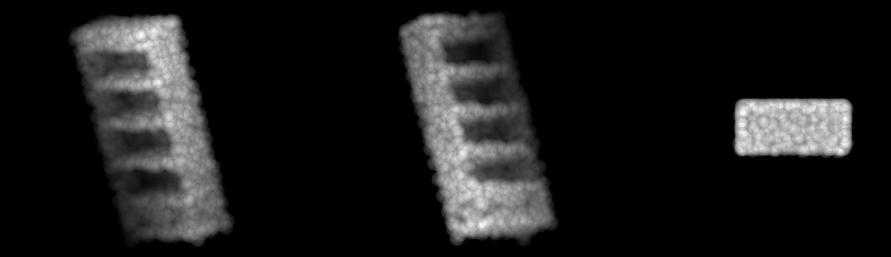




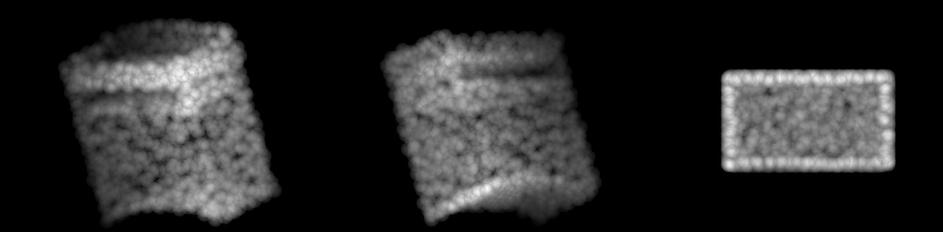
270_label_table_pred_desk.jpg





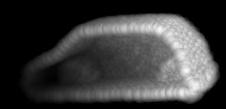


271_label_dresser_pred_bookshelf.jpg



272 label dresser pred night stand.jpg

273_label_car_pred_piano.jpg









274_label_piano_pred_tent.jpg